



D.C. Milli-Ohm Meter

GOM-804 & GOM-805

USER MANUAL

PART NO. 82OM-80500E01



ISO-9001 CERTIFIED MANUFACTURER

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S SAFETY INSTRUCTIONS

This chapter contains important safety instructions that you must follow when operating the GOM-804/805 or when keeping it in storage. Read the following before any operation to insure your safety and to keep the GOM-804/805 in the best possible condition.

Safety Symbols

These safety symbols may appear in this manual or on the GOM-804/805.



WARNING

Warning: Identifies conditions or practices that could result in injury or loss of life.



CAUTION

Caution: Identifies conditions or practices that could result in damage to the instrument or to other properties.



DANGER High Voltage



Attention Refer to the Manual



Protective Conductor Terminal



Earth (ground) Terminal



Do not dispose electronic equipment as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased.

Safety Guidelines

General Guideline



CAUTION

- Do not place any heavy objects on the instrument.
- Avoid severe impact or rough handling that leads to damaging the instrument.
- Do not discharge static electricity to the instrument.
- Use only mating connectors, not bare wires, for the terminals.
- Do not disassemble the instrument unless you are qualified as service personnel.

(Note) EN 61010-1:2010 specifies the measurement categories and their requirements as follows. The GOM-804/805 doesn't fall under category II, III or IV.

- Measurement category IV is for measurements performed at the source of low-voltage installation.
 - Measurement category III is for measurements performed in the building installation.
 - Measurement category II is for measurements performed on the circuits directly connected to the low voltage installation.
-

Power Supply



WARNING

- AC Input voltage: 100 - 240 V AC, 50 - 60Hz, 25VA
 - The power supply voltage should not fluctuate more than 10%.
 - Connect the protective grounding conductor of the AC power cord to an earth ground, to avoid electrical shock.
-

Cleaning the GOM-804/805

- Disconnect the power cord before cleaning.
 - Use a soft cloth dampened in a solution of mild detergent and water. Do not spray any liquid into the instrument.
 - Do not use chemicals or cleaners containing harsh material such as benzene, toluene, xylene, and acetone.
-

Operation Environment

- Location: Indoor, no direct sunlight, dust free, almost non-conductive pollution (Note below)
 - Relative Humidity: < 80%
 - Altitude: < 2000m
 - Temperature: 0°C to 40°C (operation)
-

(Note) EN 61010-1:2010 specifies the pollution degrees and their requirements as follows. The GOM-804/805 falls under degree 2. Pollution refers to “addition of foreign matter, solid, liquid, or gaseous (ionized gases), that may produce a reduction of dielectric strength or surface resistivity”.

- Pollution degree 1: No pollution or only dry, non-conductive pollution occurs. The pollution has no influence.
- Pollution degree 2: Normally only non-conductive pollution occurs. Occasionally, however, a temporary conductivity caused by condensation must be expected.
- Pollution degree 3: Conductive pollution occurs, or dry, non-conductive pollution occurs which becomes conductive due to condensation which is expected. In such conditions, equipment is normally protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity is controlled.

Storage Environment

- Location: Indoor
- Temperature: -10°C to 70°C

Disposal



Do not dispose this instrument as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased. Please make sure discarded electrical waste is properly recycled to reduce environmental impact.

Power cord for the United Kingdom

When using the instrument in the United Kingdom, make sure the power cord meets the following safety instructions.

NOTE: This lead / appliance must only be wired by competent persons



WARNING: THIS APPLIANCE MUST BE EARTHED

IMPORTANT: The wires in this lead are coloured in accordance with the following code:

Green/ Yellow: Earth

Blue: Neutral

Brown: Live (Phase)



As the colours of the wires in main leads may not correspond with the coloured marking identified in your plug/appliance, proceed as follows:

The wire which is coloured Green & Yellow must be connected to the Earth terminal marked with either the letter E, the earth symbol \oplus or coloured Green/Green & Yellow.

The wire which is coloured Blue must be connected to the terminal which is marked with the letter N or coloured Blue or Black.

The wire which is coloured Brown must be connected to the terminal marked with the letter L or P or coloured Brown or Red.

If in doubt, consult the instructions provided with the equipment or contact the supplier.

This cable/appliance should be protected by a suitably rated and approved HBC mains fuse: refer to the rating information on the equipment and/or user instructions for details. As a guide, a cable of 0.75mm^2 should be protected by a 3A or 5A fuse. Larger conductors would normally require 13A types, depending on the connection method used.

Any exposed wiring from a cable, plug or connection that is engaged in a live socket is extremely hazardous. If a cable or plug is deemed hazardous, turn off the mains power and remove the cable, any fuses and fuse assemblies. All hazardous wiring must be immediately destroyed and replaced in accordance to the above standard.

G ETTING STARTED

This chapter describes the GOM-804/805 in a nutshell, including its main features as well as its front and rear panels. After going through the panel overview, follow the Power-up sequence before attempting to use the instrument.

Please note the information in this manual was correct at the time of printing. However as GW Instek continues to improve its products, changes can occur at any time without notice. Please see the GW Instek website for the latest information and content.



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GOM-804/805 Characteristics

GOM-804 and GOM-805 are modern high precision programmable DC Milli-ohm meters suitable for low resistance measurements of switches, relays, connectors, PCB tracks and a variety of other devices. The meters feature a color TFT-LCD screen with easy-to-read measurement results. With the easy-to-use features, superior performance and automatic test interfaces, these meters are dependable instruments for resistance measurements.

Easy to Use Features Each test function on the GOM-804/805 can be easily activated by pressing a single front panel key. All the settings and measurement results are displayed and set on the TFT-LCD panel at the same time making each function naturally intuitive to use.

Each primary and secondary measurement result is displayed prominently on the display along with any corresponding settings. For sequential measurement results, such as those from the scan or binning function, are tabulated in an intuitive and easy-to-read format.

In addition, the meters can recall previously used settings upon startup, allowing the meter to be ready the next time it used in a matter of moments. The meters can also save or recall up to 20 sets of function settings.

Performance The GOM-804/805 has nine selectable measurement ranges from 50m Ω to 5M Ω , a constant current source of 1uA to 1A, an accuracy of up to 0.05%, a 1u Ω resolution and performs measurements using four wire Kelvin connections for accurate, consistent measurements.

The ability to choose between high accuracy measurements at 10 samples/sec (full scale at 50000 counts) or high speed measurements at 60 samples/sec (full scale at 50000 counts), allows the GOM-804/805 the flexibility to fulfill a number of different measurement roles.

| | |
|--|---|
| Advanced Temperature Measurements | <p>The GOM-804/805 has a number of advanced temperature functions that can be used with the optional temperature probe, PT-100.</p> <p>The temperature compensation function can extrapolate what the resistance of a DUT will be at a desired temperature, if the temperature coefficient of the DUT and the resistance of the DUT at ambient temperature are known.</p> <p>The temperature conversion function can be used to extrapolate what the temperature rise of a DUT will be at specified resistance if the initial resistance, initial temperature and the constant for the DUT are known.</p> |
| Drive Signals | <p>The GOM-805 can select a number of different drive signals to suit a number of different measurement scenarios, for example the Pulse setting can be used to cancel the effects of thermoelectric EMF on the measurement results.</p> |
| Dry Circuit Testing | <p>Dry circuit testing allows the GOM-805 to measure the contact resistance of switches and connectors according to the DIN IEC 512 and ASTM B539 standards. The open circuit voltage will not exceed 20mV in this mode to prevent the oxidization layer on metal switches and connector points from breakdown. GOM-805 only.</p> |
| Automatic Testing | <p>For automatic testing The GOM-804/805 has a handler interface designed for automatic testing. The handler interface outputs the status of PASS, FAIL, HI, LO, READY and EOT signals and inputs a trigger control signal. Automatic testing is used with the binning, compare and scan functions.</p> <p>For computer control applications, RS-232 and USB are standard remote interfaces, with GPIB as standard only for the GOM-805 and GOM-804G.</p> |

Applications

- Production testing for contact resistance of switches, relays, connectors, cables and printed circuit boards and other low resistance devices.
 - Component testing of resistors, motors, fuses and heating elements.
 - Incoming inspection and quality assurance testing.
 - Conductivity evaluation for product design.
-

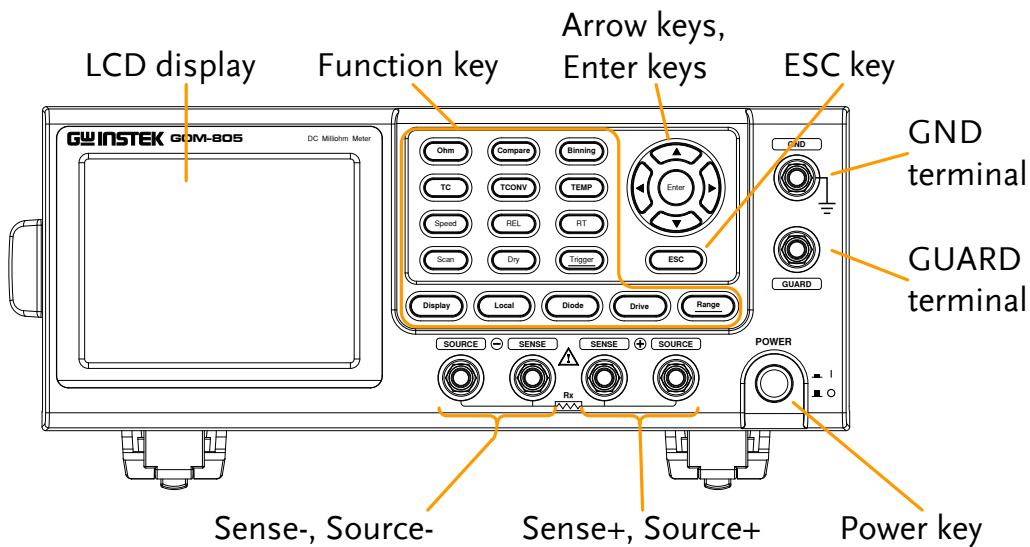
Key Features

- 50,000 counts
 - Measurement Range: 50m Ω ~5M Ω
 - Accuracy of up to 0.05%
 - Compare function
 - Binning function
 - Manual or Auto-ranging
 - Continuous or Triggered measurement modes
 - Temperature measurement, temperature compensation and temperature conversion
 - Four-wire Kelvin measurement method
 - Selectable power-on settings
 - Diode test
 - Alarm settings for function-specific PASS/FAIL test results
 - Sampling rate: 10 or 60 sampling/sec
 - Standard interfaces:
USB/RS232/Scan/Handler/GPIB(GOM-805,
GOM-804G)
 - Save/Recall settings: 20 memory sets
 - External I/O logic function
-

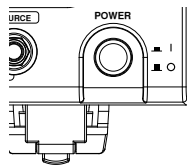
Model Lineup



| Feature / Model | GOM-804 | GOM-804G* | GOM-805 |
|---|---------|-----------|---------|
| Ohm Measurement | ✓ | ✓ | ✓ |
| Compare Function | ✓ | ✓ | ✓ |
| Diode Measurement | ✓ | ✓ | ✓ |
| Temp. Compensation | ✓ | ✓ | ✓ |
| Temp. Conversion | ✓ | ✓ | ✓ |
| Temp Measurement | ✓ | ✓ | ✓ |
| Dry Circuit | ✗ | ✗ | ✓ |
| Drive Selection | ✗ | ✗ | ✓ |
| Binning Function | ✗ | ✗ | ✓ |
| GPIB Interface | ✗ | ✓ | ✓ |
| <p>* The GOM-804G is simply the GOM-804 with the factory-installed GPIB option. Please note that the GPIB option cannot be user-installed on the GOM-804. The option must be ordered prior to purchase.</p> | | | |

Front Panel Overview



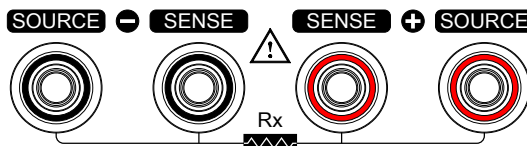
Power Switch



Turns On  or Off  the main power. For details about the power up sequence, see page 24.

Measurement Terminals

Source, Sense Terminals



Sense + and Sense - terminals.

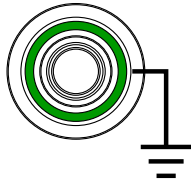







Current source terminals: Source + and Source -.



When measuring components with polarity, connect Source+ to the positive potential and connect Source- to the negative potential of the component.



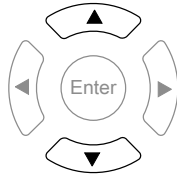
Discharge any DUT before measurement to avoid damaging the GOM-804/805.

| | | |
|----------------|---|---|
| GND Terminal |  | Connect the GND (ground) terminal to the earth ground. |
| GUARD Terminal |  | The GUARD terminal has the same potential as earth, but cannot be substituted for it. Connect the GUARD terminal to the cable shield layer of the test leads to help reduce noise. |
| Function Keys |  | The Ohm key activates the resistance measurement function. |
| |  | The Compare key activates the comparator function. |
| |  | The Binning key activates the binning function to grade the DUTs into eight bins according to the tolerance settings. GOM-805 only. |
| |  | The TC key activates the TC (temperature compensation) function which calculates the resistance of a DUT at a specified temperature given the resistance of the DUT at the ambient temperature and the temperature coefficient of the DUT is known. |
| |  | The TCONV (Temperature Conversion) function calculates the temperature of a DUT given an initial temperature, initial resistance, measured resistance and a constant (inferred zero resistance temperature) for the DUT. |
| |  | The TEMP key activates the temperature measurement function. |

| | |
|----------------|---|
| Speed | The Speed key toggles between 10 samples per second and 60 samples per second (Slow rate and Fast rate). |
| REL | The REL key is used to perform a zero adjustment to the test leads or a DUT. |
| RT | The RT key is used to display the real-time (not averaged) measured resistance value. |
| Scan | The Scan key is used to turn on the Scan function. |
| Dry | The Dry key is used to turn on the dry circuit measurement mode which allows the GOM-805 to measure the contact resistance of switches and connectors according to DIN IEC 512 and ASTM B539 standards. GOM-805 only. |
| Trigger | <p>When in the internal trigger mode, pressing the Trigger key will turn on the external trigger mode. When in the external trigger mode, pressing the Trigger key will perform a manual trigger.</p> <p>A long press of the Trigger key when in external trigger mode will reset the trigger mode back to the internal trigger mode.</p> |
| Display | The Display key toggles between the standard display mode and the simplified display mode (sans menus and display icons). |
| Local | The LOCAL key will switch the milliohm meter between local and remote mode. |
| Diode | The Diode key is used to turn on the Diode measurement function. |

Drive

+



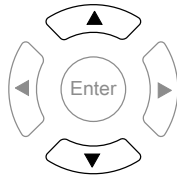
The Drive key in conjunction with the up/down arrow keys is used to select the measuring signal: DC+, DC-, Pulse, PWM, Zero. In particular, the Zero setting can be used as a +/-10mV DC voltmeter to measure the EMF of passive components. See page 33 for details. GOM-805 only. The drive signal is fixed to DC+ on the GOM-804.

Range

Long pressing the Range key will activate the auto ranging mode.

Range

+



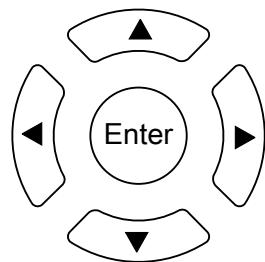
The Range key in conjunction with the up/down arrow keys is used to select the resistance measurement range.

When in auto ranging mode, pressing the Range key will activate the manual ranging mode.

ESC

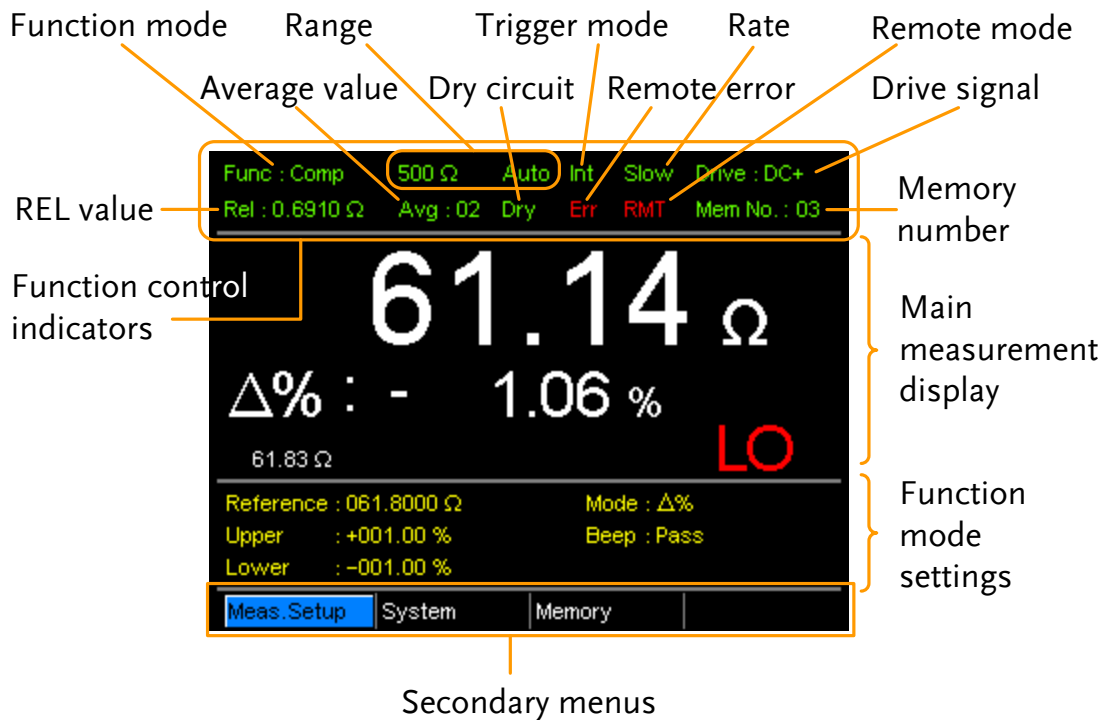
The ESC key cancels the current setting and returns the cursor to its default location or returns to the previous menu, depending on the circumstances.

Arrow Keys,
Enter Key



The arrow keys and Enter key are used to edit parameters, to navigate the menu system and to select parameter ranges.

TFT-LCD Overview



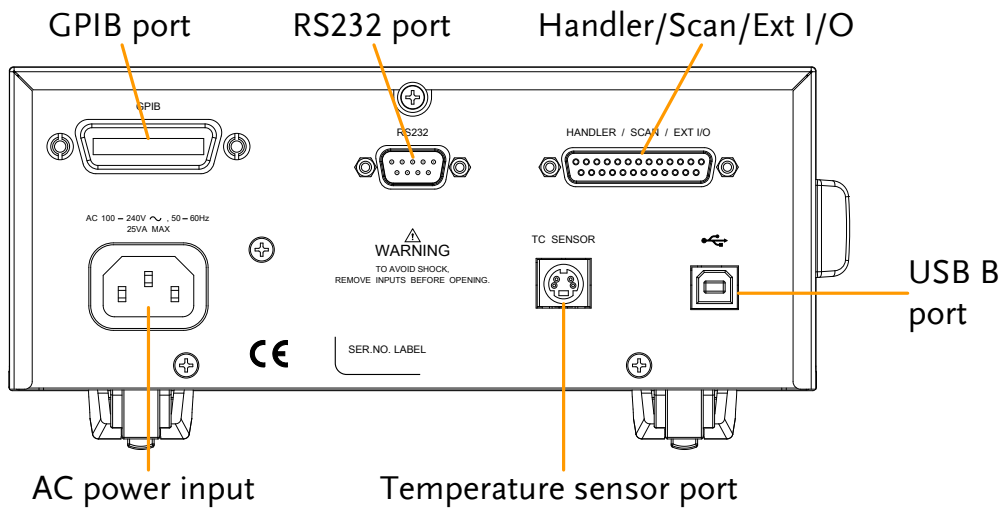
Function Control Indicators

The function control indicators show all the currently active settings for the selected function mode:

| | |
|--------------|---|
| Func | Currently selected function mode |
| Range | The measurement range. Auto indicates that auto ranging is active |
| Trigger mode | Int/Ext |
| Rate | Slow/Fast |
| Drive: | DC+, DC-, Pulse, PWM, Zero |
| Rel | Shows the relative (nominal) reference value |
| Avg | Number of samples used for the Average function. |
| Dry | Indicates that the dry circuit function is active |
| Err | Indicates a remote command error |

| | | |
|--------------------------|--|---|
| | RMT | Indicates that the unit is in remote control mode |
| | Mem No. | Indicates which memory setting has been recalled |
| Main Measurement Display | Shows all measurement results for the selected function mode. | |
| Function Mode Settings | Shows any function mode-specific settings. | |
| Secondary Menus | The secondary menus show global menus (Meas. Setup), System, Memory) as well as function-specific secondary menus. | |
| | Meas. Setup | Goes to the global Measurement Setup menu. |
| | System | Goes to the global System menu |
| | Memory | Allows you to save, recall and clear memory settings. |
| | View | Shows the all results for all the channels when a scan has finished. |
| | Clear | Clears the measurement results in the Binning function when the display mode is set to Count. |

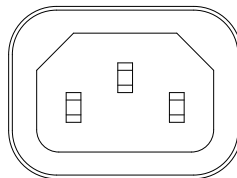
Rear Panel Overview



AC Input

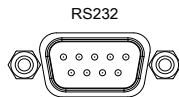
AC 100 - 240V ~ , 50 - 60Hz
25VA MAX

Accepts the power cord. AC 100 - 240Vac; 50 - 60Hz.



For the power up sequence, see page 24.

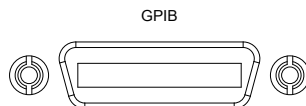
RS-232 Port



Accepts an RS-232C cable for remote control; DB-9 male connector.

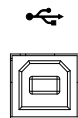
For remote control details, see page 92.

GPIB Port



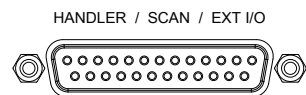
Accepts a GPIB cable for remote control. See page 93 for details.

USB Device Port



USB device port for remote control. See page 90 for details.

Handler / Scan / EXT I/O Port



The Handler / Scan / EXT I/O port is used to output pass/fail/high/low comparison results. This port is also used for the user-programmable EXT I/O pins.

Temperature
Sensor Port

TC SENSOR



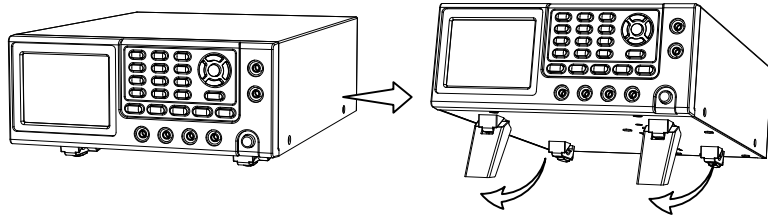
The temperature sensor input is for the optional PT-100 temperature probe.

Set Up

Tilt Stand

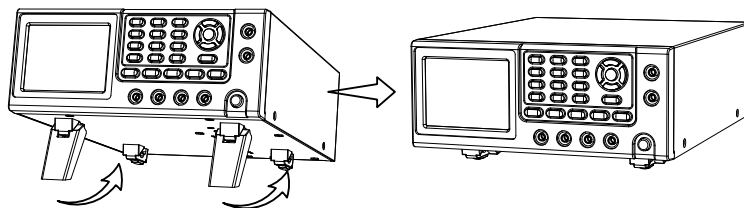
Tilt

To tilt, pull the legs forward, as shown below.



Stand Upright

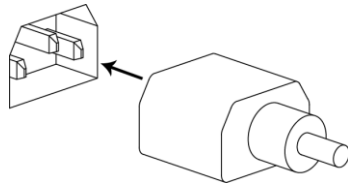
To stand the unit upright, push the legs back under the casing as shown below.



Power Up

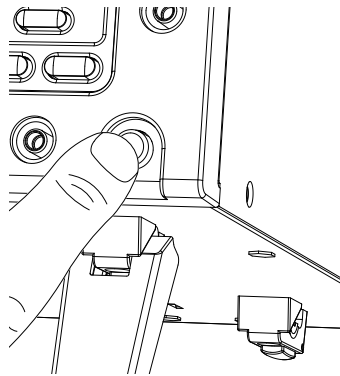
1. Connection Ensure that the input AC power voltage is within the range of 100~240 V.

Connect the power cord to the AC Voltage input.



Ensure the ground connector of the power cord is connected to a safety ground. This will affect the measurement accuracy.

1. Power up Press the main power switch on the front panel.



The display will light up and show the last setting used before the last shut down.

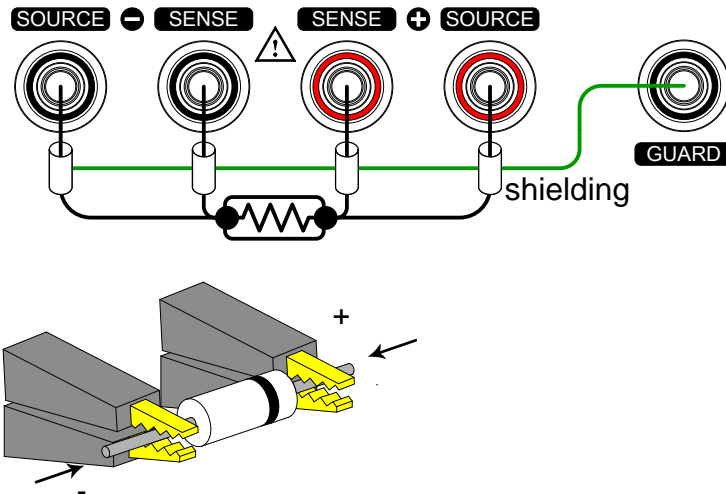
Example:
Resistance
measurement
mode



4 Wire Kelvin Connection

Background The GOM-804/805 uses 4 wire Kelvin connections for accurate measurements.

Connection Diagram



| | | |
|-------------|----------|---|
| Description | Source + | The Source + terminal carries the measuring current source. It is connected to the + side of the DUT. |
| | Source - | The Source - terminal accepts the signal return current and connects to the - side of the DUT. |
| | Sense + | Monitors the positive (+) potential. |
| | Sense - | Monitors the negative (-) potential. |
| | Guard | Grounds the shielding layer of the test lead cables to reduce noise. |
| | GND | Provides a reference ground for the GOM-804/805. |

Zeroing (Relative Function)

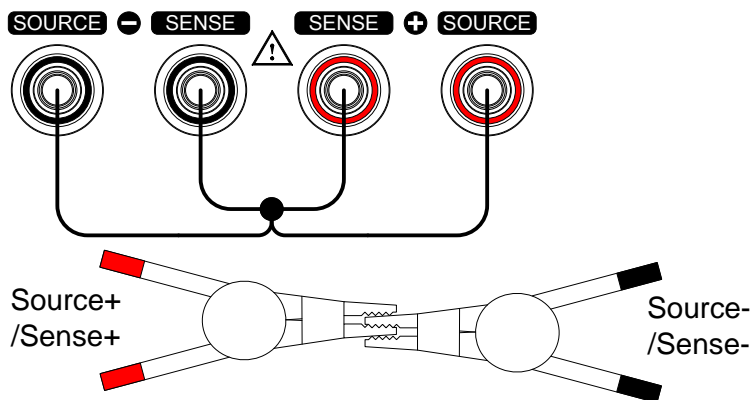
Background

The Relative function is used to perform a zero adjustment on the test leads.

After the Relative value is pre-set, each measurement that is displayed is equal to the actual value minus the relative preset value.

1. Short the cables

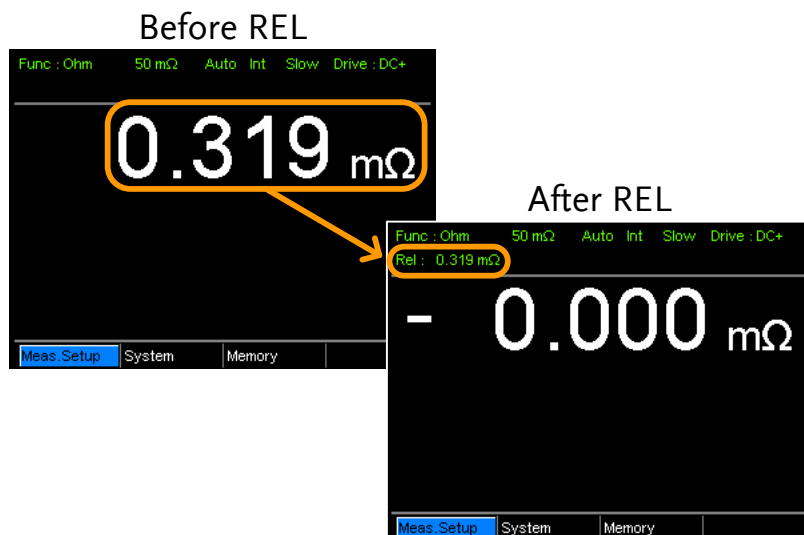
Short the test cables together as shown in the diagram below:



2. Set the Reference value

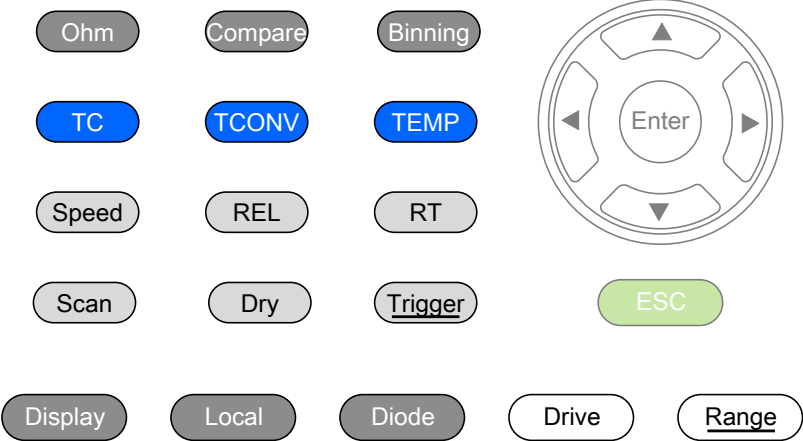
Press the **REL** key.

3. Relative mode display appears



Rel: Indicates the Relative function is active

M EASUREMENT



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|------------------|--|
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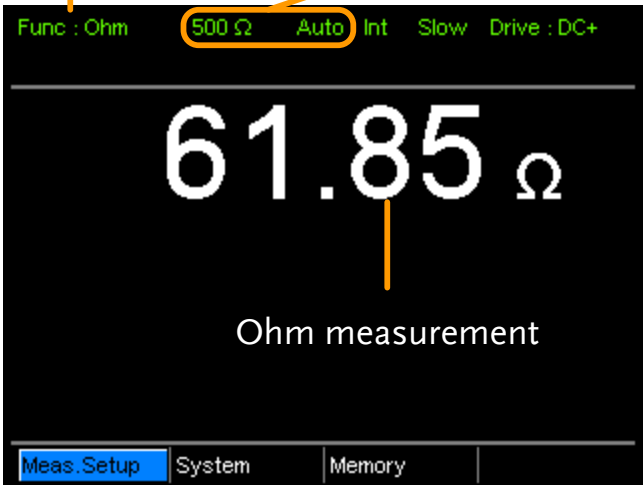
Resistance Measurement

1. Select the Resistance function.

Press **Ohm** to access the Resistance measurement mode.

2. Resistance mode display appears.

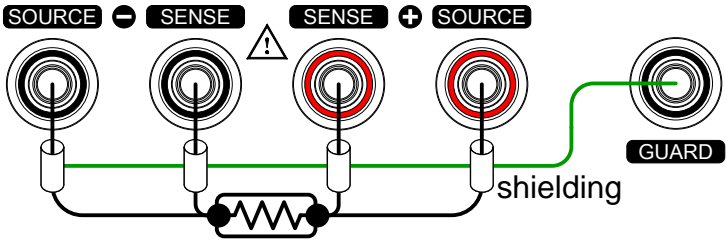
Ohm measurement function indicator Resistance range and mode



3. Connect the test lead and measure

4-wire resistance:

Use the SOURCE + and the SOURCE - terminal for measurement, and the SENSE +, and SENSE - terminal for sensing.



 Note

When switching between measurement ranges, please allow a moment for the circuits to settle before measuring.

Select the Resistance Range

Background The resistance range can be used with normal resistance measurement as well as the temperature compensation function.

Manual Press the **Range** key and use the up and down arrow keys to manually select the resistance range.



Auto Range Long press the **Range** key to turn on automatic ranging.

Range, Auto range



| Selection List | Range | Resolution |
|----------------|-------|------------|
| | 50mΩ | 1uΩ |
| | 500mΩ | 10uΩ |
| | 5Ω | 100uΩ |
| | 50Ω | 1mΩ |
| | 500Ω | 10mΩ |
| | 5kΩ | 100mΩ |
| | 50kΩ | 1Ω |
| | 500kΩ | 10Ω |
| | 5MΩ | 100Ω |



Note

For detailed specifications, please see the specifications on page 152.

Measuring Signal (Drive) Overview

Background Resistance measurement has 5 different measuring signals that can be applied to obtain a resistance measurement: DC+, DC-, Pulse, PWM, Zero. These 5 signals are described in below.



Note

The drive function is only applicable to the GOM-805. The drive signal for the GOM-804 is fixed to DC+.

DC+

Default drive signal.

DC-

Negative drive signal.

Pulse

This mode can be used to eliminate the thermoelectric EMF formed on the contact between a test lead and a DUT.

PWM

This mode can be used to avoid heating up the DUT and thus avoid having the measurement accuracy compromised on temperature-sensitive DUTs.

Zero

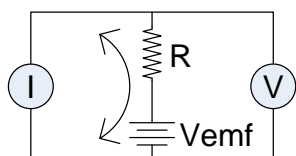
In this mode, GOM-805 outputs no measuring signal on the Source loop; therefore, the Sense loop can be used as a voltage meter which can measure up to +/-10mV for thermoelectric EMF measurement. This function is useful for measuring the V_{emf} of thermocouple wires.

A note about Thermoelectric EMF

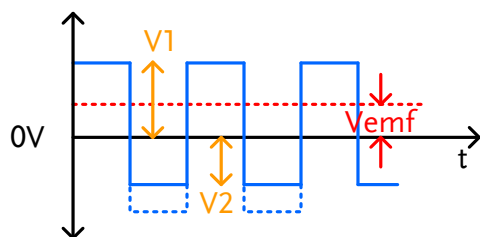
When making low resistance measurements, thermoelectric electromotive force (V_{emf}) can affect measurement accuracy. V_{emf} is created at the junction of two dissimilar metals, such as the contact point of a test lead and the pin of a DUT. V_{emf} adds a small but measurable voltage to the measurement.

There are primarily two different methods to compensate for V_{emf} in low resistance measurements: Offset Compensation and V_{emf} Cancelling. The GOM-805 uses V_{emf} Cancelling with the pulse drive signal setting (see page 33).

The Pulse drive mode supplies a positive and a negative measurement current source.



This produces a positive and negative measurement voltage across the DUT, which also includes the V_{emf} ($V_1 + V_{emf}$ & $V_2 + V_{emf}$).




To cancel the V_{emf} , V_2 is deducted from V_1 and divided by 2 to get the average measurement, as shown in the formula below:


$$V_x = \frac{(V_1 + V_{emf}) - (V_2 + V_{emf})}{2}$$

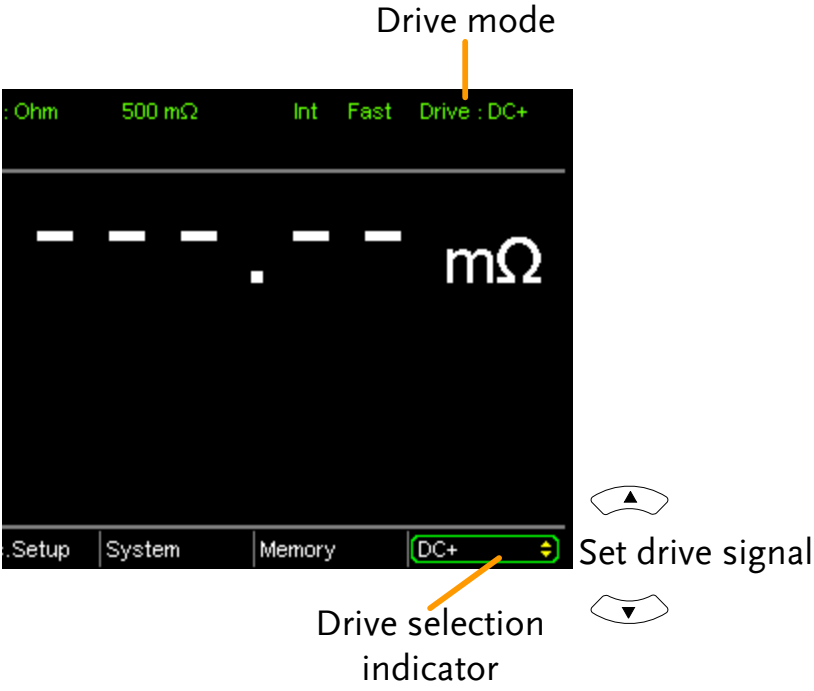
Where V_x = measured voltage sans V_{emf} .

Select Measuring Signal (Drive)

Background Resistance measurement has 5 different measuring signals that can be applied to obtain a resistance measurement: DC+, DC-, Pulse, PWM, Zero.

 **Note** The drive function is only applicable to the GOM-805. The drive signal for the GOM-804 is fixed to DC+.

1. Select Drive Press the  key and use the up and down arrow keys to select a drive signal.




Drive Range DC+, DC-, Pulse, PWM, Zero

Select Measurement Rate

Background The resistance measurement speed has 2 ranges: slow and fast. Slow speed is the most accurate with 10 measurements/second. Fast speed has 60 measurements/second. Both have the same measurement resolution.

The rate selection function is not applicable in Diode measurement mode. When the PWM drive signal is used or when the Scan function is activated, the only available rate setting is fast.

1. Select Rate Press the  key to toggle between the Slow and Fast rates.

Measurement rate



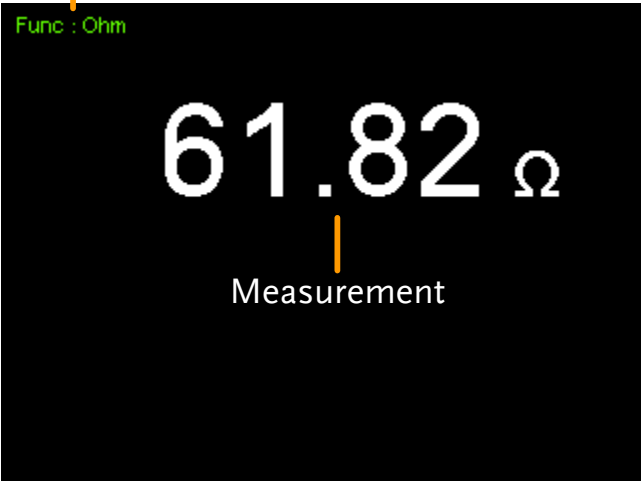
Display Mode

Background The Display key can be used to toggle between the normal and the simplified display mode. The simplified display mode clears all text, menus and function indicators from the screen except for the measurement and measurement mode indicators.

1. Toggle Display mode Press the  key to toggle the display between normal and simplified. The display will change accordingly.

Simplified Display Mode Example

Measurement mode



View Real-Time Measurement

Background When measurements are smoothed using the averaging function, the RT key can be used to view the real-time results in addition to the averaged results.

See page 60 for Average configuration.

1. Toggle Real-Time display

Press the  key to toggle the real-time display on or off.

The real-time measurement will appear in the bottom left-hand corner.



Real-time measurement

Dry-Circuit Measurement

Background The Dry Circuit measurement function is used where the maximum open-circuit voltage must be kept to a minimum for applications such as measuring the contact resistance of switches, relays and connectors. The GOM-805 provides a maximum of up to 20mV in this mode.




Note

Dry circuit testing is for switch and connector contact resistance. Switch and connector contact resistance measurement is in accordance with DIN IEC 512 and ASTM B539 which requires that the open circuit voltage of the measuring device should not exceed 20mV DC. Voltage at such low levels avoids the breakdown of any oxides that may be present on the contacts. In this mode the open circuit measuring voltage is limited <20mV, while modes like DC+ or pulse mode can have an open circuit measuring voltage as high as 6.5V.

Dry Limitations When the Dry Circuit measurement function is turned on, the measurement range is reduced. See the specifications for more details.

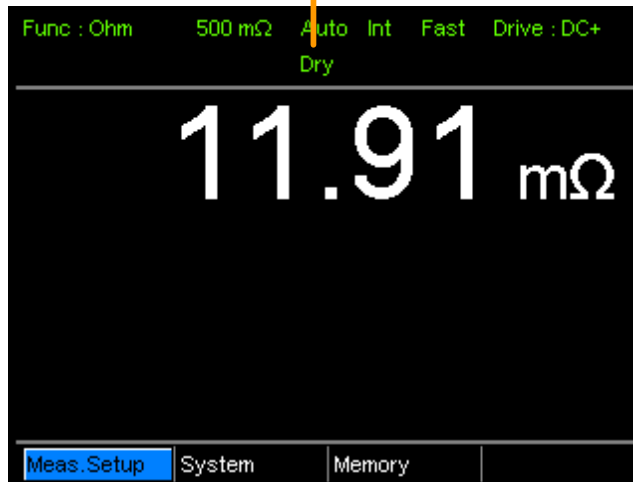
| Range | Dry Mode | Rate |
|-------|----------|-----------|
| 50mΩ | ✗ | |
| 500mΩ | ✓ | Slow/Fast |
| 5Ω | ✓ | Slow/Fast |
| 50Ω | ✓ | Slow/Fast |
| 500Ω | ✗ | |
| 5kΩ | ✗ | |
| 50kΩ | ✗ | |
| 500kΩ | ✗ | |
| 5MΩ | ✗ | |

1. Toggle Dry mode on or off

Press the  key to toggle the dry circuit measurement mode on or off.

The DRY function indicator will appear in the middle of the display when active.

Dry Circuit measurement mode indicator



Using the Trigger Function

Background

The GOM-804/805 can use internal or manual triggering for the Resistance, Temperature, Temperature Compensation, Temperature Conversion, Binning, Handler and Scan modes. By default the GOM-804/805 is set to internal triggering mode.

1. Select Manual Trigger


Short press  to switch to manual triggering mode.

The Ext indicator will be shown on the display when the manual trigger is active.

Trigger source



2. Manually Triggering Measurements

Short press the  key each time you want to start a single measurement (when in the manual mode).

3. Internal Triggering

Long press **Trigger** to return the triggering mode back to internal mode.

The Int indicator will be shown on the display.

Internal trigger source

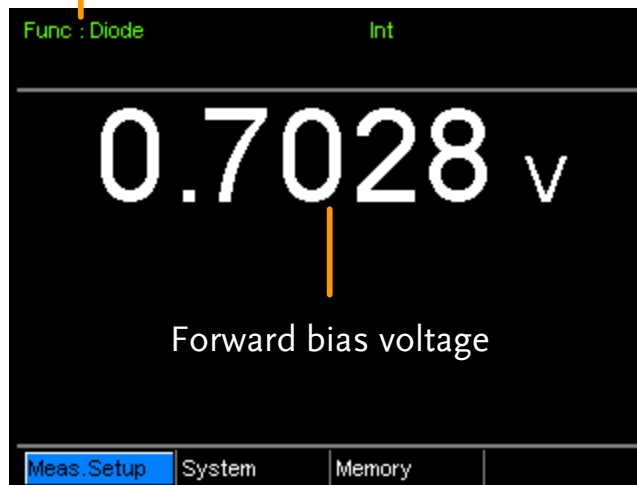


Diode Function

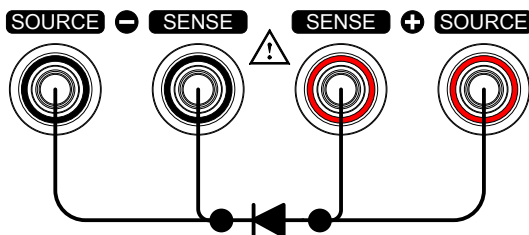
Background The Diode function can be used to measure the forward bias voltage of a diode under test.

1. Select the Diode function. Press **Diode** to access the Diode measurement mode.

2. Diode mode appears. Diode function indicator



3. Connect the test lead and measure. Connect the Sense+, Source+ to the anode. Connect the Sense-, Source- to the cathode.



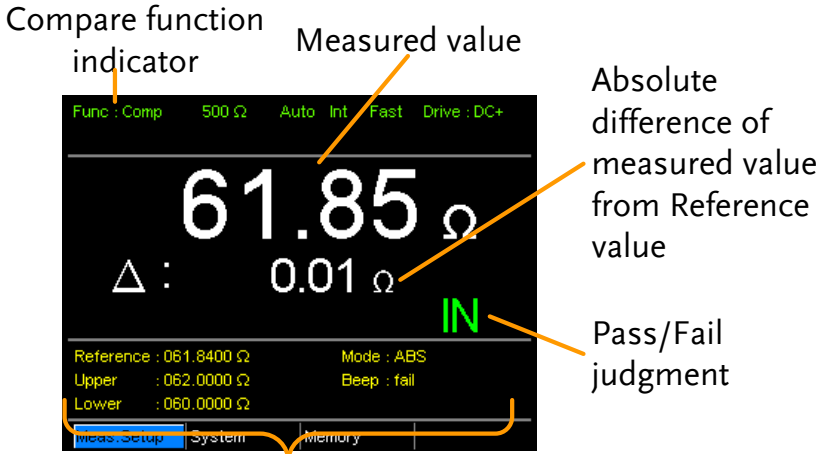
Compare Function

Background

The compare function compares a measured value to a “Reference” value that has an upper (HI) and lower (LO) limit. If the measured value is within the upper and lower limit, then the measured value is judged as IN.

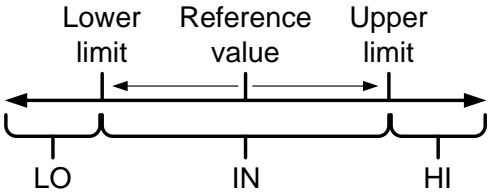
There are three compare modes that can be used to make a judgment: ABS, $\Delta\%$ and $\%$ modes.

The ABS mode displays the absolute difference between the measured and the reference value (shown as Δ) and compares the measured value to the upper (HI) and lower (LO) limit. The upper and lower limits are set as absolute resistance values.



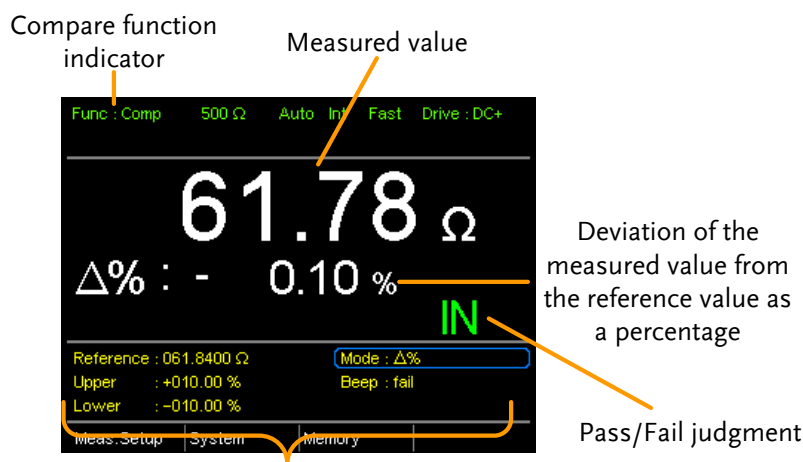
Reference, limits, compare mode and beep mode

A measured value that falls within the upper and lower limits is considered IN (pass), a value that falls below the lower limits is considered LO, and a value that falls over the upper limit is a HI.



[Note that the reference value in the ABS mode is only for reference purposes and is not used to make a judgment.]

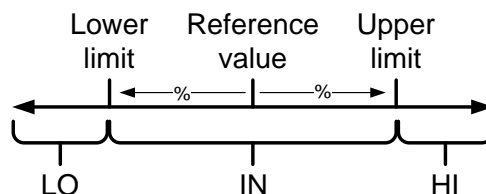
The $\Delta\%$ compare function displays the deviation of the measured value from the reference value as a percentage. $\{ [(Measured\ Value - Reference) / Reference] \% \}$.



Reference, limits, compare mode and beep mode

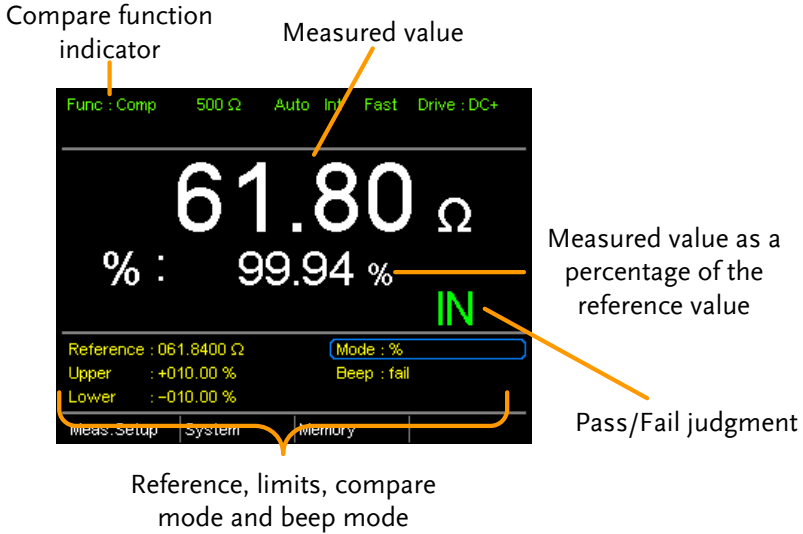
The upper (HI) and low (LO) limits are set as a percentage *from* the reference value. (Identical to the % compare mode)

A measured value that falls within the upper and lower limits is considered IN (pass), a value that falls below the lower limits is considered LO, and a value that falls over the upper limit is a HI.

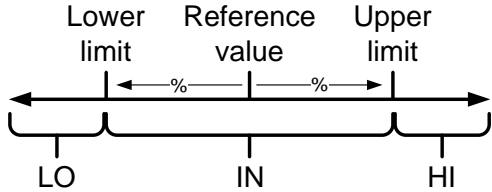


The % compare mode displays the measured value as a percentage of the reference value $[(Measured\ Value / Reference\ Value) \%]$.

The upper (HI) and low (LO) limits are set as a percentage *from* the reference value. (Identical to the $\Delta\%$ compare mode)



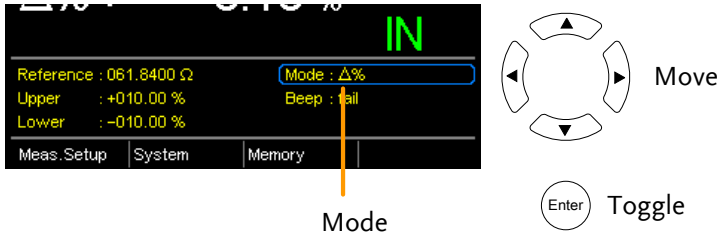
A measured value that falls within the upper and lower limits is considered IN (pass), a value that falls below the lower limits is considered LO, and a value that falls over the upper limit is a HI.



For all the compare modes, IN, HI or LO will be shown on the display for each judgment.

1. Select the compare function above. Press **Compare** to access the compare mode, as shown

2. Select the compare mode Use the arrow keys to navigate to the Mode setting. Press the Enter key to toggle the compare mode.

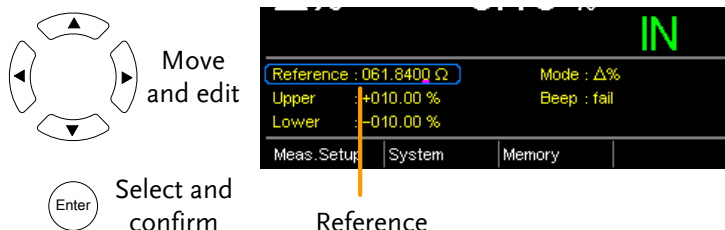


Range Abs, Δ, %, %

3. Reference value setting

Use the arrow keys to navigate to the Reference setting and press Enter.

Use the left and right arrow keys to select a digit. Use the up and down arrow keys to edit the value of the selected digit and the unit. Press Enter to confirm the setting.



Range: 000.0001 ~ 999.9999
(mΩ/Ω/kΩ/MΩ)



Note

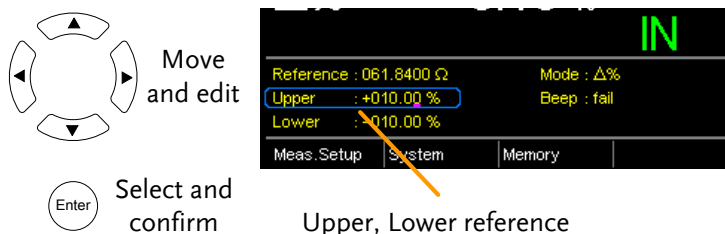
After setting the Reference value, the displayed Δ , % or $\Delta\%$ values will be changed to reflect the new Reference value setting.

4. Upper & lower limit setting

Use the arrow keys to navigate to the Upper or Lower limit setting and press Enter.

Use the left and right arrow keys to select a digit. Use the up and down arrow keys to edit the value of the selected digit. Press Enter to confirm the setting.

Repeat for the other limit (Upper or Lower).



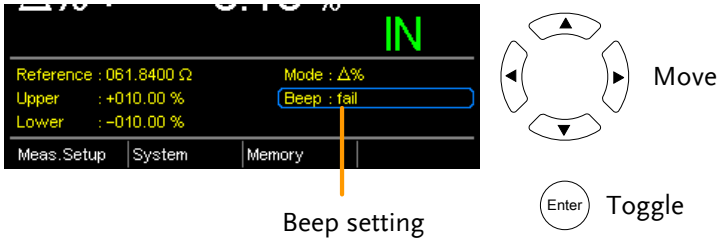
Setting Range: ABS mode: 000.0000 ~ 999.9999
(mΩ/Ω/kΩ/MΩ)
 $\Delta\%$ and % mode:
-999.99 ~ +999.99



Note

The upper limit must be higher than the lower limit. Not setting the upper limit higher than the lower limit is not allowed. Likewise the lower limit cannot be set higher than the upper limit.

5. Beep setting Use the arrow keys to navigate to the Beep setting.
Press Enter to toggle the beep setting.



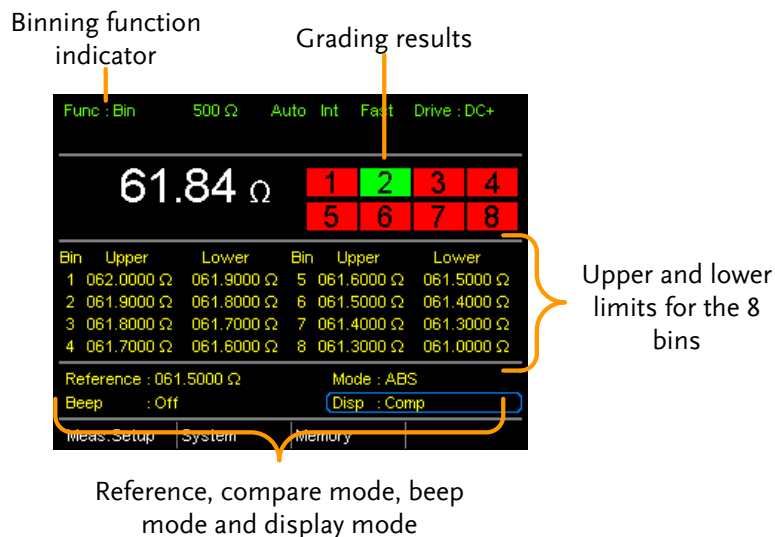
Beep Setting: Off, Pass, Fail



The Beep setting can also be set from the System>Utility>Beep>Compare menu.

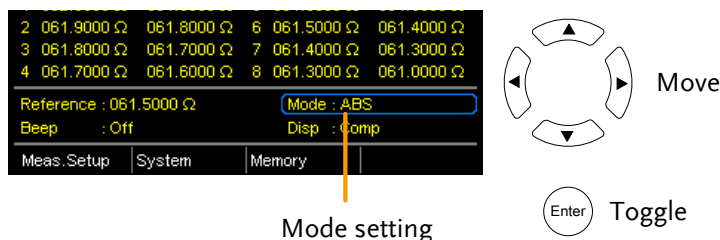
Binning Function

Background The Binning function is used to grade DUTs into eight different bins according to 8 sets of upper and lower limits. Two compare modes can be used in this function, ABS and $\Delta\%$ modes.



1. Select the Binning function Press the **Binning** key to access this function.

2. Select the compare mode Use the arrow keys to go to the Mode setting. Press Enter to toggle between ABS or $\Delta\%$ compare modes.



ABS Mode The ABS mode allows you to set the upper and lower limits of each bin as absolute resistance values.

$\Delta\%$ The Delta % mode allows you to set the upper and lower limits of each bin as percentage value from the reference value.



Note

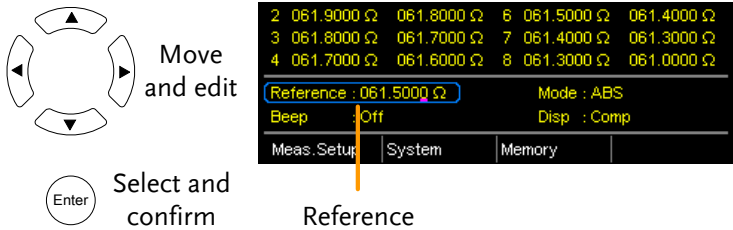
For further details on the ABS or $\Delta\%$ compare modes, see the description in the Compare section, page 41.

3. Reference value setting

Although the 8 bins have their own upper and lower limits, they still share a common reference value.

Use the arrow keys to go to the Reference setting and press Enter.

Use the left and right arrow keys to select a digit. Use the up and down arrow keys to edit the value of the selected digit and the unit. Press Enter to confirm the setting.



Range 000.0001 ~ 999.9999 (mΩ/Ω/kΩ/MΩ)

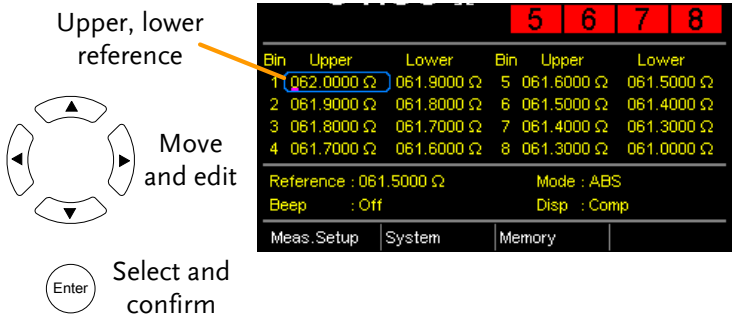
4. Upper & lower limit settings

Use the arrow keys to go to the upper limit of the first bin and press Enter.

Use the Left and Right arrow keys to select a digit. Use the Up and Down arrow keys to edit the value of the selected digit and unit. Press the Enter key to confirm the setting.

Repeat for the lower setting.

Repeat for the remaining bins.



Setting range ABS mode: 000.0000~999.9999 (mΩ/Ω/kΩ/MΩ)
 $\Delta\%$ mode: -999.99 ~ +999.99

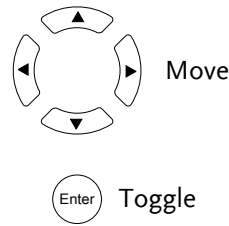
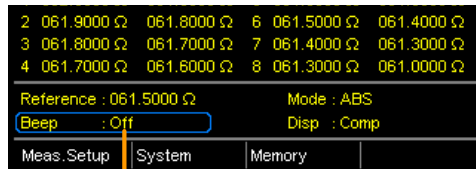


Note

The upper limit must be higher than the lower limit. Not setting the upper limit higher than the lower limit is not allowed. Likewise the lower limit cannot be set higher than the upper limit.

5. Beep setting

Use the arrow keys to navigate to the Beep setting. Press Enter to toggle the beep setting.



Beep setting

Beep Setting: Off, Pass, Fail



Note

The Beep setting can also be set from the System>Utility>Beep>Binning menu.

6. To start binning

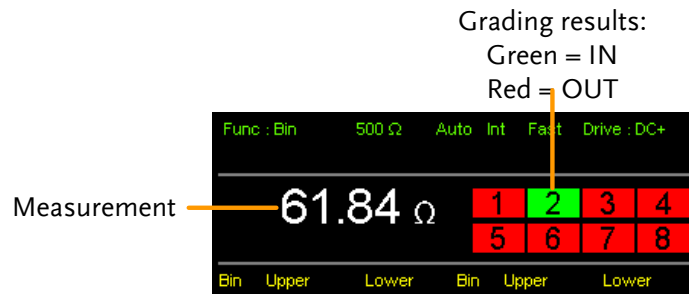
The binning function starts automatically if you are in internal trigger mode.

If you are using the manual triggering mode, press the **Trigger** button or apply a pulse on the trigger pin of the Handler interface to start binning.

See page 38 to set the triggering modes.

7. Display the binning results

There are two different display modes to view results. The Comp (Compare) display mode is the default display mode. This mode will display the currently measured value and displays which of the bins (if any) the measured value is graded as.



The Count display mode tabulates the results on the right-hand side of the display and shows the bin settings on the left.

Tabulated result of each bin

| Bin | Upper | Lower | In | Out | Result |
|-----|------------|------------|------|-------|--------|
| 1 | 062.0000 Ω | 061.9000 Ω | 641 | | |
| 2 | 061.9000 Ω | 061.8000 Ω | 1289 | | |
| 3 | 061.8000 Ω | 061.7000 Ω | 228 | | |
| 4 | 061.7000 Ω | 061.6000 Ω | 95 | | |
| 5 | 061.6000 Ω | 061.5000 Ω | 74 | 793 | |
| 6 | 061.5000 Ω | 061.4000 Ω | 42 | | |
| 7 | 061.4000 Ω | 061.3000 Ω | 48 | | |
| 8 | 061.3000 Ω | 061.0000 Ω | 53 | | |
| | | | | Total | 3263 |

Func : Bin 500 Ω Auto Ext Fast Drive : DC+

Reference : 061.5000 Ω Mode : ABS

Beep : Off Disp : Count

Meas. Setup System Memory Clear

Overall results

Clear results

Upper and lower limits of Bin 1~8

To toggle the display mode, go to the Disp setting and press Enter.

Disp setting

Move

Enter Toggle

8. How to clear the result count

When in the Count display mode, press the **ESC** key. Go to the Clear setting and press Enter. The accumulated results will be cleared from the display.

Disp : Count

System Memory Clear

Clear setting

Move

Enter Clear results

Temperature Measurement

Background The temperature measurement function uses the optional PT-100 temperature probe. The measured temperature is displayed on the display. For more information on the optional PT-100 sensor, see the appendix on page 149.

There is only one range for the temperature function. However the resistance measurement range can still be changed when in the temperature function.

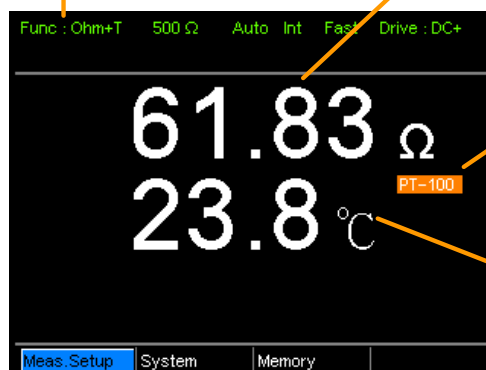
Note: The temperature measurement function is used in conjunction with the Ohm measurement function. The two measurements share the same display, so the Ohm readings stay on the display even after the temperature measurement function is activated. Thus when the Temperature function is selected, “Ohm+T” is shown as the selected function.

1. Select the Temperature function

Press **TEMP** to enter the temperature measurement function.

Temperature + Ohm function indicator

Resistance measurement



(Ambient) temperature source

Ambient temperature

The temperature is displayed on the Ohm display.

2. Select the temperature units

From the bottom menu, go to Meas. Setup>Temperature Unit and select °C or °F.

See page 65 for setting details.

3. Ambient Temperature

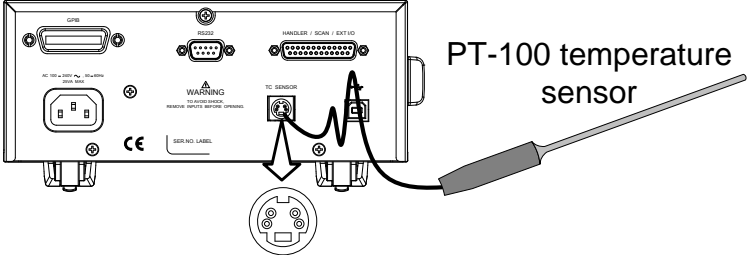
The Ambient temperature setting should be turned off when using the temperature function.

From the bottom menu go to Meas. Setup > Ambient Temperature and turn the Ambient Temperature setting off.

See page 66 for setting details.

4. Temperature mode connection

The temperature sensor uses the rear panel TC Sensor port for input.



Temperature Compensation

Background

If the resistance of a DUT at a particular temperature is needed, the compensation function can be used. This function can simulate the resistance of a DUT at a desired temperature. If the ambient temperature and the temperature coefficient of the DUT are known, it is possible to determine the resistance of a DUT at any temperature.

The Temperature Compensation works on the following formula:

$$R_{t0} = \frac{R_t}{1 + \alpha_{t0}(t - t_0)}$$

Where:

R_t = Measured resistance value (Ω)

R_{t0} = Corrected resistance value (Ω)

T_0 = Inferred absolute temperature

t_0 = Corrected temperature ($^{\circ}\text{C}$)

t = Current ambient temperature ($^{\circ}\text{C}$)

α_{t0} = Temperature coefficient of resistance at the correct

temperature. $\alpha_{t0} = \frac{1}{|T_0| + t_0}$.

1. Select the Temperature Compensation mode

Press **TC** to access the Temperature Compensation function.

The temperature-compensated resistance measurement will appear on the display.

Temperature compensation function indicator

Extrapolated resistance measurement at the desired ("correct") temperature

Ambient temperature source

Ambient temperature

Correct Temperature, Temperature Coefficient settings

2. Ambient Temperature

The ambient temperature can be either measured with the PT-100 sensor or be set manually.

If using the PT-100 sensor the Ambient temperature setting should be turned off. If the PT-100 probe is not used, then the ambient temperature needs to be manually set.

From the bottom menu, go to Meas. Setup > Ambient Temperature and set the ambient temperature.

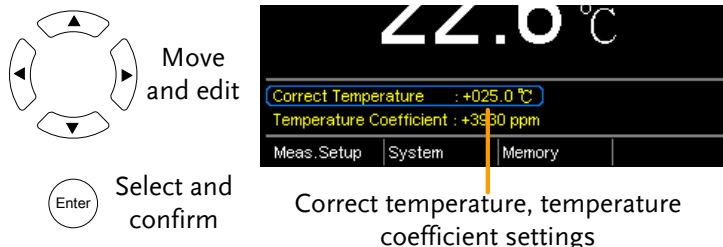
See page 66 for setting details.

Range Off, -50.0 °C ~ 399.9°C

3. Temperature compensation

Use arrow keys to go to Correct Temperature or to Temperature Coefficient and press Enter to select the setting.

To edit the setting values use the left and right arrow keys to select a digit and use the up and down arrow keys to edit the digit. Press Enter to confirm the setting.



Desired Temperature range -50.0 ~ +399.9 °C

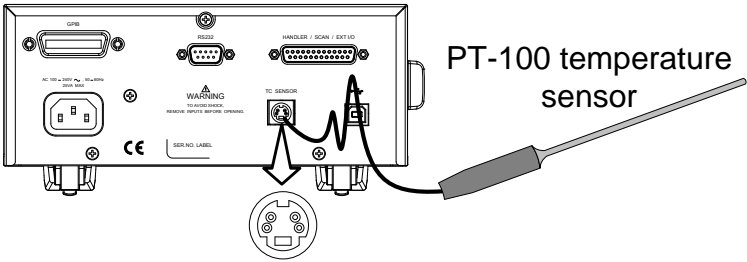
Temperature Coefficient range -9999 ~ +9999 ppm

Below are the inferred zero resistance temperatures of some common conductors:

| Material | Inferred Absolute Temperatures |
|-----------|--------------------------------|
| Silver | -243 |
| Copper | -234.5 |
| Gold | -274 |
| Aluminium | -236 |
| Tungsten | -204 |
| Nickel | -147 |
| Iron | -162 |

3. Temperature compensation connection

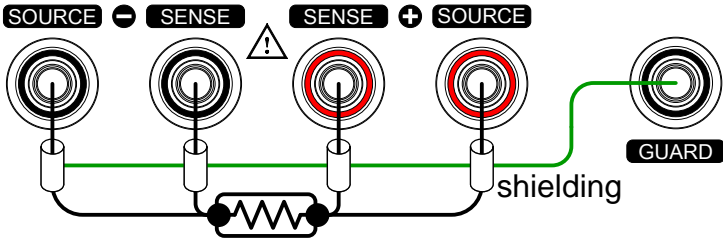
Sensor Connection:



Note: If the sensor is not connected, then the Ambient temperature needs to be manually set.

DUT connection:

4 wire Kelvin:



Temperature Conversion

Background

The Temperature Conversion function allows you to determine the temperature change of a DUT at any given resistance, if the initial temperature, the inferred zero resistance temperature for the DUT and the initial resistance of the DUT are known. The displayed result can also be extrapolated to calculate the final temperature (T) or the extrapolated temperature difference (ΔT)*.

Temperature Conversion function works on the following formula:

$$\frac{R_2}{R_1} = \frac{t_0 + t_2}{t_0 + t_1}$$

Where:

R_2 = resistance @ temperature t_2

R_1 = resistance @ temperature t_1

t_0 = inferred zero resistance temperature in °C**

t_1 = temperature at R_1

t_2 = temperature at R_2

The temperature conversion function is can be used to determine the temperature of transformer windings, electric motors, or other materials where it may not be practical to embed a temperature sensor.

$$*(T) \text{ Final temperature} = t_2 = \Delta T + T_A$$

(T_A) Ambient temperature = Ambient temperature when R_2 is measured. T_A can either be manually measured with the PT-100 sensor or it can be manually set.

$$(\Delta T) \text{ Extrapolated temperature difference} = T - T_A$$

**“Constant” setting on the panel display is equivalent to the absolute value of the inferred zero resistance temperature.

Common inferred zero resistance temperatures

Metallic conductors show increased resistivity when temperature is increased, and likewise show reduced resistivity when temperature is reduced. Inferred zero resistance temperature is simply the inferred temperature at which the material will have no resistance. This value is derived from the temperature coefficient of the material. Note: the inferred zero resistance temperature is an ideal value, and not a real-world value.

| Material | Inferred zero resistance temp. in °C |
|-----------|--------------------------------------|
| Silver | -243 |
| Copper | -234.5 |
| Gold | -274 |
| Aluminium | -236 |
| Tungsten | -204 |
| Nickel | -147 |
| Iron | -162 |

1. Select the Temperature compensation mode.

Press TCONV to access the temperature compensation function.

The temperature-converted measurement will appear on the display.

Temperature conversion function indicator

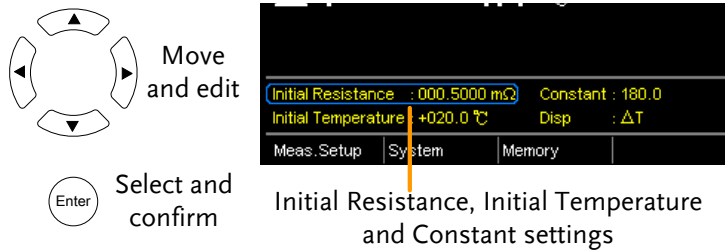
Resistance measurement

(Ambient) temperature source

Extrapolated temperature difference or final temperature

2. Initial Resistance, Initial Temperature and Constant settings

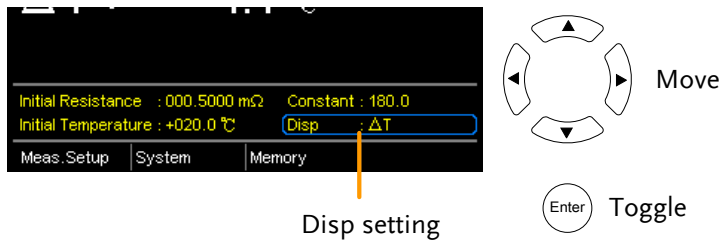
Use the arrows keys to go to Initial Resistance, Initial Temperature or Constant (inferred initial resistance temperature) and press Enter.
 Use the left and right arrow keys to select a digit and use the up and down arrow keys to edit the digit. Press Enter to confirm the edit.



| | |
|---------------------|---------------------------------|
| Initial Resistance | 000.0001~999.9999 mΩ, Ω, kΩ, MΩ |
| Initial Temperature | -50.0 ~ +399.9 °C |
| Constant | 000.0~999.9 |

3. Display mode

Use the arrow keys to go to Disp. Press Enter to toggle between the T and ΔT modes.

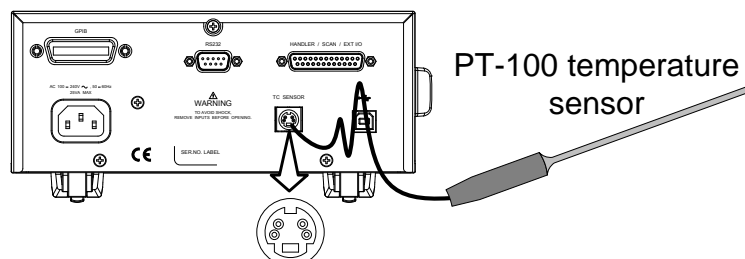


T displays the extrapolated temperature at the measured resistance of the DUT.

ΔT displays the difference from the extrapolated temperature at the measured resistance of the DUT and the ambient temperature. Please refer to page 56 for further details.

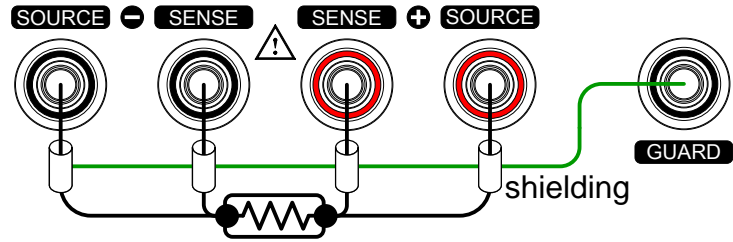
3. Temperature compensation connection.

Sensor Connection:



DUT connection

4 wire Kelvin:



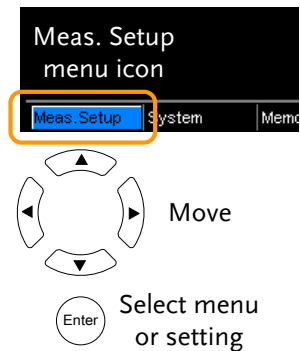
Measurement Settings

Background The following measurement settings are used to configure the various measurement modes.

Average Function

Background The average function smoothes measurements using a moving average. The average function sets the number of samples used for the moving average; a higher number results in smoother measurement results. The average function is turned off by default.

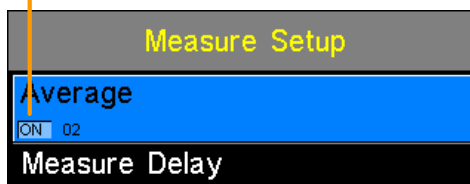
1. Select Average setting From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



Go to Meas. Setup and press Enter.
Go to Average and press Enter.

2. Average setting appears Use the arrow keys to turn Average on and set the average number. Press Enter to confirm the setting.

Average settings



Average OFF, ON: 2~10



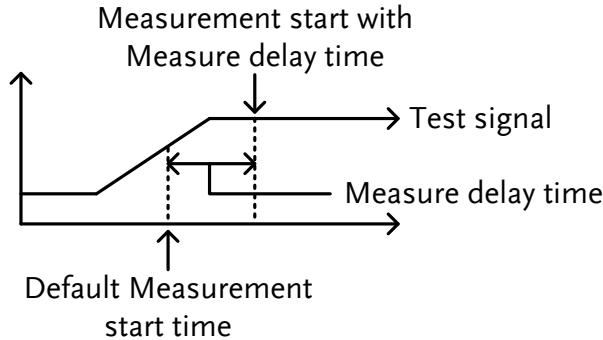
Note

Pressing ESC before pressing ENTER will exit the Average function settings.

Measure Delay

Background

The Measure Delay setting inserts a delay time between each measurement. Measure delay is turned off by default.



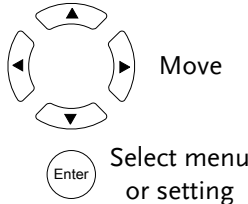
The measure delay setting is useful for measuring components that need some time to charge if the default measurement start time is not adequate. An adequate delay time allows the meter to avoid the effects of transient disturbances that are usually seen when measuring reactive DUTs with a current source.

1. Select Measure Delay setting

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.

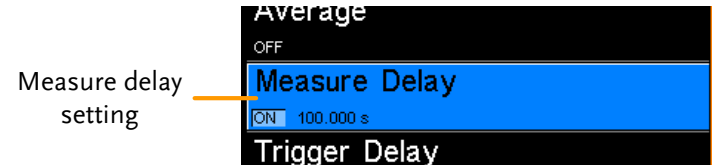


Go to Meas. Setup and press Enter. Go to Measure Delay and press Enter.



2. Measure Delay setting appears

Use the arrow keys to turn Measure Delay on and set the delay time. Press Enter to confirm the setting.



Measure Delay* OFF, ON: 000.000 ~ 100.000s

* When the set value is > 0.1s, the resolution is 0.1s. When the set value is < 0.1S, the resolution is 1mS.



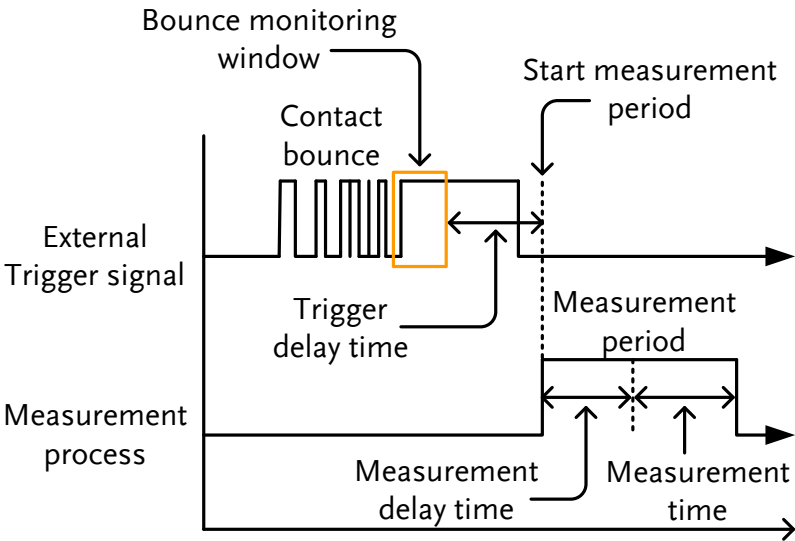
Note

Pressing ESC before pressing ENTER will exit the Measure Delay settings.

Trigger Delay

Background

The Trigger Delay setting adds a delay to when an external trigger signal is recognized. Normally the external trigger is recognized when there is no contact bounce in the signal for a fixed length of time, this time is known as the bounce monitoring window. This ensures that the external trigger signal is stable before it is recognized. The Trigger Delay time starts right after the bounce monitoring window ends.



The Trigger Delay setting is turned off by default.



Note

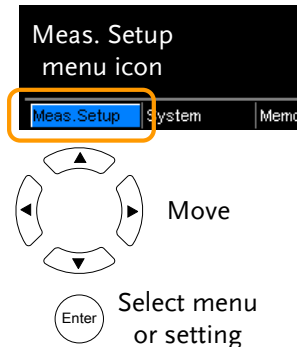
Pin 2 of the Handler/Scan/Ext I/O interface is used for external triggering, See page 77 for pinout details.

1. Select Trigger Delay setting

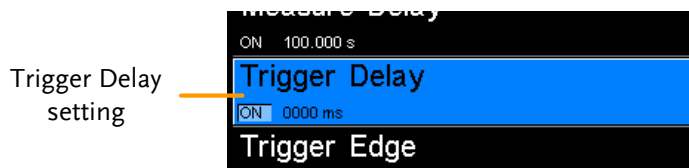
From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.

Go to Meas. Setup and press Enter.

Go to Trigger Delay and press Enter.



2. Trigger Delay setting appears Use the arrow keys to turn Trigger Delay on and set the delay time. Press Enter to confirm the settings.



Trigger Delay OFF, ON: 0 ~ 1000ms



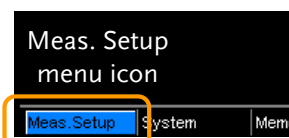
Note

Pressing ESC before pressing ENTER will exit the Trigger Delay settings.

Trigger Edge

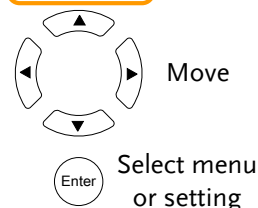
Background The Trigger Edge setting sets the external trigger edge as rising or falling. By default the trigger edge is set to rising.

1. Select Trigger Edge setting From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



Go to Meas. Setup and press Enter.

Go to Trigger Edge and press Enter.



2. Trigger Edge setting appears Use the arrow keys to set the Trigger Edge. Press Enter to confirm the setting.



Trigger Edge Rising, Falling



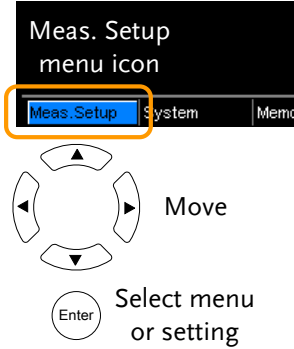
Note

Pressing ESC before pressing ENTER will exit the Trigger Edge settings.

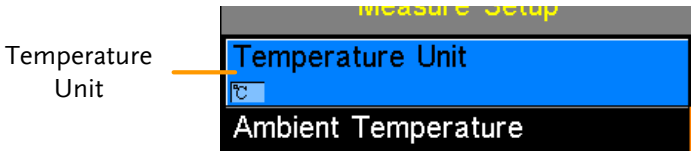
Temperature Unit

Background Temperature units can be set to Fahrenheit or Celsius for all temperature measurements.

1. Select Temperature Unit setting From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.
Go to Meas. Setup and press Enter.
Go to Temperature Unit and press Enter.



2. Temperature Unit setting appears Use the arrow keys to set the Temperature Unit. Press Enter to confirm the setting.



Temperature Unit Fahrenheit, Celsius

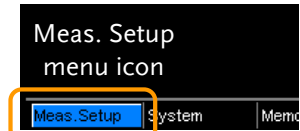
 **Note**

Pressing ESC before pressing ENTER will exit the Temperature Unit setting.

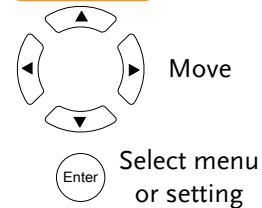
Ambient Temperature

Background The Ambient Temperature setting is used to set the ambient (room temperature) for the Temperature Compensation or Temperature Conversion function in the absence of the PT-100 temperature sensor. See page 52 and 56 respectively for details.

1. **Select Ambient Temperature setting** From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.

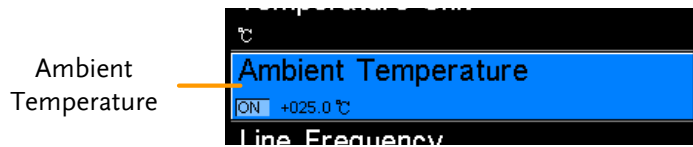


Go to Meas. Setup and press Enter.
Go to Ambient Temperature and press Enter.



2. **Ambient Temperature setting appears**

Use the arrow keys to set the Ambient Temperature. Press Enter to confirm the setting.



Ambient Temperature Off, On: -50°C ~ 399.9°C



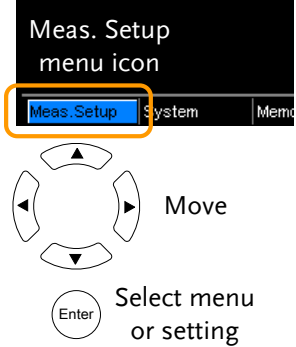
Note

Pressing ESC before pressing ENTER will exit the Ambient Temperature setting.

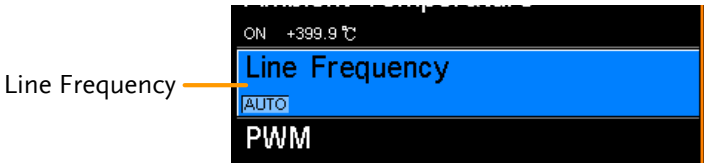
Line Frequency

Background The Line Frequency setting selects the appropriate line filter to reduce the influence of the AC line frequency on the milliohm measurements. This setting is set to AUTO by default.

1. Select Line Frequency setting From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.
Go to Meas. Setup and press Enter.
Go to Line Frequency and press Enter.



2. Line Frequency setting appears Use the arrow keys to set the Line Frequency. Press Enter to confirm the setting.



Line Frequency Auto, 50Hz, 60Hz

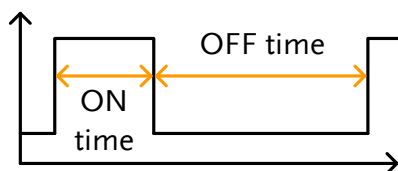
 **Note**

Pressing ESC before pressing ENTER will exit the Line Frequency setting.

PWM Setting

Background

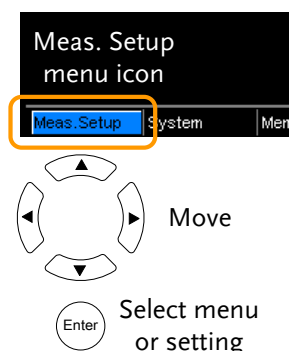
The PWM setting will set the duty of the PWM Drive setting. The duty is set with ON and OFF times for the waveform.



See page 31 for Drive setting details.

1. Select PWM setting

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.

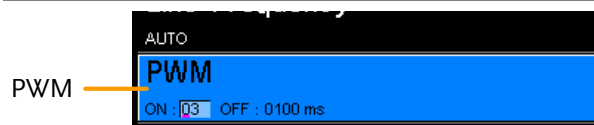


Go to Meas. Setup and press Enter.

Go to PWM and press Enter.

2. PWM setting appears

Use the arrow keys to set the ON and OFF time for the duty. Press Enter to confirm the setting.



| | |
|-----|---------------------|
| ON | 03 ~ 99 time units* |
| OFF | 0100 ~ 9999 ms |

*The ON time setting is set in “time units”, not milliseconds. The amount of time in a time unit depends on the line frequency settings (see page 67).

| Line frequency | 1 Time Unit |
|----------------|-------------|
| 60Hz | 16.6mS |
| 50Hz | 20mS |



Note

Pressing ESC before pressing ENTER will exit the PWM setting.

System Settings

Background The System settings are used to view the system information, set the power on state, the remote interface, screen brightness, external interface and beep settings as well as access the calibration menu.

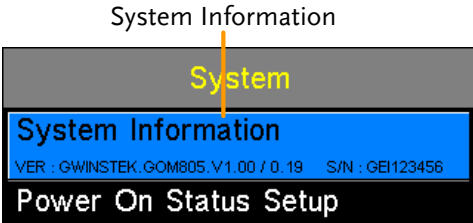
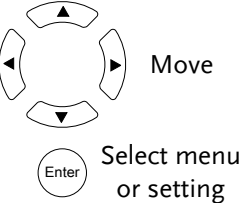
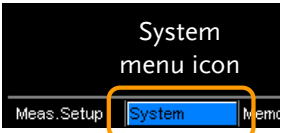
System Information

Background The System Information will show the manufacturer, model, software version and serial number of the unit. The system information is the equivalent of the return string from the *idn? query (page 144).

1. View System Information

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.

Go to System and press Enter. System information will be displayed at the top of the System menu.



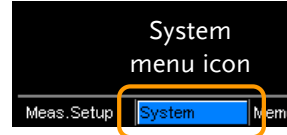
Pressing ESC will exit from the System menu.

Power On Status Setup

Background The Power On Status Setup allows you to either load the previous settings or the default settings on startup.

1. Select Power On Status setting

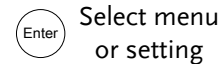
From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



Go to System and press Enter.

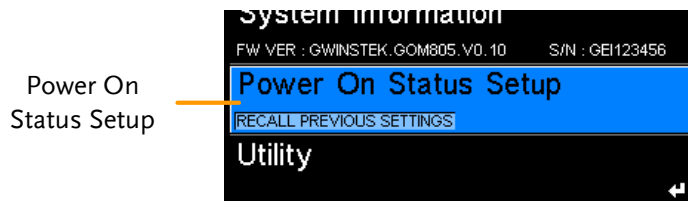


Go to Power On Status Setup and press Enter.



2. Power On Status Setup appears

Use the arrow keys to set Power ON Status Setup. Press Enter to confirm the setting.



Power On Status Recall Previous Settings, Load Default



Note

Pressing ESC before pressing ENTER will exit the Power On Status Setup.

Interface

Background The remote interface can be set to RS232, GPIB or USB.

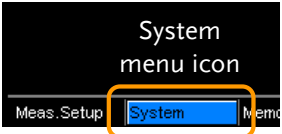


Note

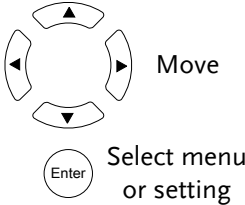
The GPIB interface is only available on the GOM-804G and the GOM-805.

1. Select Interface setting

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



Go to System and press Enter.
Go to Utility and press Enter.
Go to Interface and press Enter.



2. Interface setting appears

Use the arrow keys to choose an interface and to set the baud rate (RS232) or primary address (GPIB). Press Enter to confirm the setting.



| | |
|-----------|--|
| Interface | GPIB, Primary Address (1 ~ 30) |
| | RS232, Baud Rate (1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200) |
| | USB |



Note

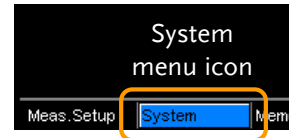
Pressing ESC before pressing ENTER will exit from the Interface settings.

Brightness

Background The Brightness setting sets the backlight brightness of the TFT-LCD panel.

1. Select Brightness setting

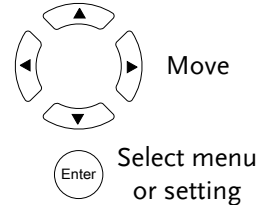
From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



Go to System and press Enter.

Go to Utility and press Enter.

Go to Brightness and press Enter.



2. Brightness setting appears

Use the arrow keys to set the brightness level. Press Enter to confirm the setting.



Brightness 01 (dim) ~ 05 (bright)



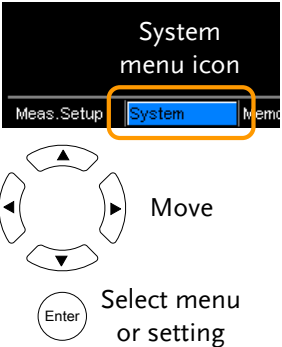
Note

Pressing ESC before pressing ENTER will exit from the Brightness settings.

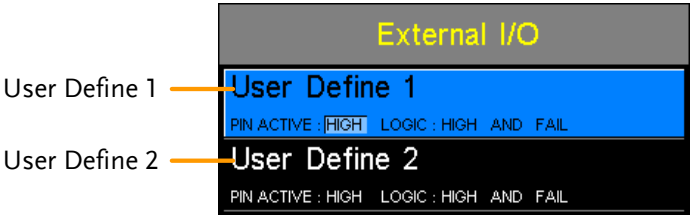
User Define Pins

Background The External I/O User Define Pin settings set the logic and the active level for the Define 1 and Define 2 pins on the Handler/Scan/EXT I/O port on the rear panel. The External I/O pins are used with the compare or bin functions. The logic settings can be based on the pass, fail, high, low or bin grade results of the selected function.

- 1. Select External I/O Setting** From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.
Go to System and press Enter.
Go to Utility and press Enter.
Go to External I/O and press Enter.



- 2. External I/O Menu Appears** Use the arrow keys to choose either User Define 1 or User Define 2 and press Enter.
Use the arrow keys to set the active level of the pin when the logic conditions are true and to set the logic settings. Press Enter to confirm the settings.



User Define 1/2: Pin Active: High, Low

Logic:

| Operand1 | Operator | Operand2 |
|-----------|-------------|-----------|
| Fail | | Fail |
| Pass | Logical OR, | Pass |
| Low | Logical | Low |
| High | AND, | High |
| Bin O** | OFF* | Bin O** |
| Bin 1 ~ 8 | | Bin 1 ~ 8 |

*The OFF operator sets the Logic as true when Operand1 is true.

** Bin 0 is defined as outside bin 1~ 8.



Note

The Bin logic settings are not available for the GOM-804.

Pressing ESC before pressing ENTER will exit from the selected External I/O setting.

Handler Mode

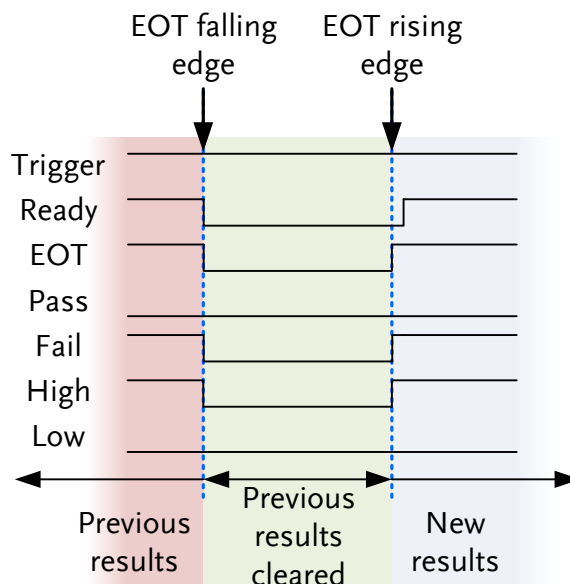
Background

The Handler Mode setting determines the behavior of the result signals from the handler interface. There are two settings, Clear and Hold. The Clear setting will clear the results of the previous test before starting the succeeding one and the Hold setting will keep the test result of the previous test until the succeeding test has completed.

The timing diagrams below are used as examples. All the result signals in the examples are active high.

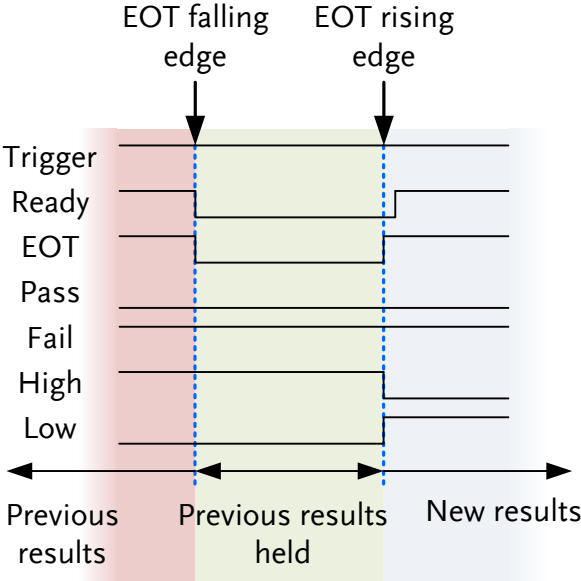
Clear example

Clear: All result signals (PASS, Fail, High and Low) are cleared at the falling edge of EOT and the results from the current test are output at the rising edge of the EOT signal.



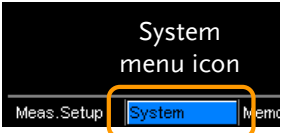
Hold example

Hold: The results of the previous tests are held until the current test has completed.

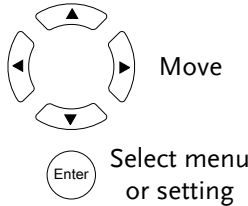


1. Select External I/O setting

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



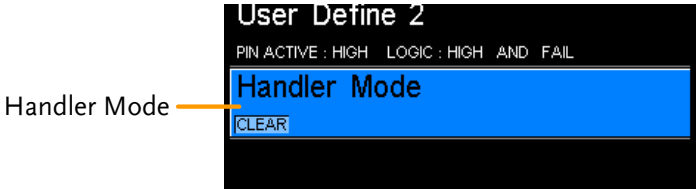
Go to System and press Enter.
Go to Utility and press Enter.
Go to External I/O and press Enter.



2. External I/O menu appears

Use the arrow keys to choose Handler Mode and press Enter.

Use the arrow keys to set the handler mode. Press Enter to confirm the setting.



Handler Mode HOLD, CLEAR

 Note

Pressing ESC before pressing ENTER will exit from the Handler Mode setting.

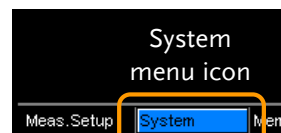
Beep

Background The Beep setting will configure the beeper sound for the key presses, the Compare function and the Binning function.

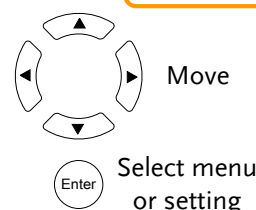
For the Compare and Binning function the beep can be configured to beep on a pass or fail judgment.

1. Select Beep setting

From one of the main screens, press the **ESC** key so that the menu system at the bottom of the display has focus.



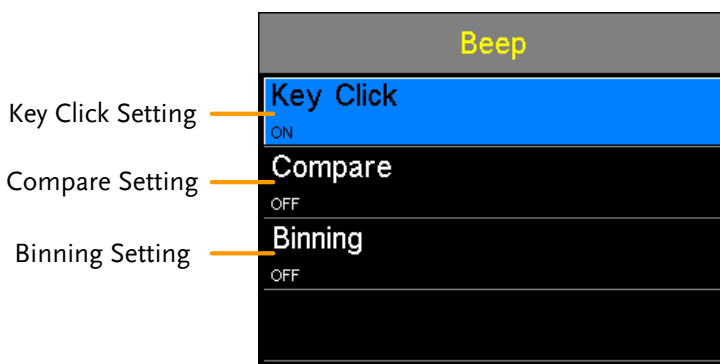
- Go to System and press Enter.
- Go to Utility and press Enter.
- Go to Beep and press Enter.



2. Beep menu appears

Use the arrow keys to choose a beep setting and press Enter.

Use the arrow keys to set the selected setting and press Enter to confirm.



| | | |
|----------------|-----------|-----------------|
| Beep Settings: | Key Click | On, Off |
| | Compare | Off. Pass, Fail |
| | Binning | Off. Pass, Fail |



Note

Pressing ESC before pressing ENTER will exit from the selected Beep setting.

HANDLER/SCAN INTERFACE

| | | |
|--------------------------|--|----|
| Handler | Handler Overview..... | 78 |
| | Pin Definitions for the Handler Interface | 80 |
| | Handler Interface for Binning and Compare Functions | 80 |
| Scan | Scan Overview..... | 82 |
| | Pin Definitions for the SCAN Interface..... | 83 |
| | Scan Interface | 83 |
| | Scan Setup | 84 |
| | Scan Output..... | 88 |
| GOM-802 Compatibility | GOM-802 Compatibility for Scan and Handler Interfaces | 89 |
| | GOM-805 to GOM-802 Handler/Scan Interface | 89 |
| Remote Interface | Configure USB Interface..... | 90 |
| | Install USB Driver | 91 |
| | Configure RS-232 Interface..... | 92 |
| | Configure GPIB Interface | 93 |
| | RS232/USB Function Check | 93 |
| | Using Realterm to Establish a Remote Connection | 94 |
| | GPIB Function | 96 |

Handler Overview

Background The Handler interface is used to help grade components based on the Compare or Binning function test results. The appropriate pins on the handler interface are active when the Compare or Binning function is used.

There are 17 TTL outputs and 1 TTL inputs. The Handler interface is only applicable with the Binning function or Compare measurement modes.



Note

Please see following pages for related functions and settings:

Compare function: 41

Binning function: 46

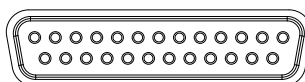
Ext I/O settings: 73

Handler mode settings 74

Interface and pin assignment

25-Pin D-SUB
(Female)

HANDLER / SCAN / EXT I/O



Pin assignment

TRIGGER

Starts the trigger for a single measurement.

READY

High when the measurement has finished. The instrument is ready for the next trigger.

EOT

High when the AD conversion has completed. The DUT is ready to be changed.

BIN 1~8

High when the sorting result is in one of the eight bin grades. Bin1~8 (pass).

BIN OUT

High when the sorting result is out of all the eight bin grades (Bin1~8). The status of this pin reflects either a HI or LO result (fail).

LOW

High when the compare result is deemed LO.

HIGH

High when the compare result is deemed HI.

HANDLER/SCAN INTERFACE

| | |
|------|---|
| FAIL | High when the compare result is either HI or LO (fail). |
| PASS | High when the compare result is IN (pass). |

For the full pin definition, please refer to the table listed below.



Note

The output current from all the pins and the VINT(+5V) pin cannot exceed 60mA.

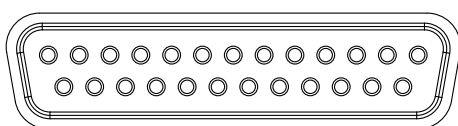
Pin Definitions for the Handler Interface

As this interface is used for the handler and scan functions, the interface pinout depends on the function mode. The following pinout is only applicable when using the Binning or Compare function.

HANDLER / SCAN / EXT I/O

13

1



25

14

Handler Interface for Binning and Compare Functions

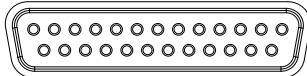
| Pin | Name | Description | Active modes | In/Out |
|-----------|---------|--|------------------|--------|
| 1, 17 | | Reserved | | |
| 2 | Trigger | Trigger for a single measurement. | All | In |
| 3, 14, 18 | GND | Ground. | | |
| 4 | Fail | High when the compare result is either HI or LO (fail). | Compare | Out |
| 5 | High | High when the compare result is deemed HI. | Compare | Out |
| 6 | Pass | High when the compare result is IN (pass). | Compare | Out |
| 7 | EOT | High when the AD conversion has completed. The DUT is ready to be changed. | Ext trigger mode | Out |
| 8 | VINT | Internal DC Voltage +5V. | | Out |
| 9 | Bin1 | High when the binning sorting result is within the bin1 setting range. | Binning | Out |
| 10 | Bin2 | High when the binning sorting result is within the bin2 setting range. | Binning | Out |
| 11 | Bin3 | High when the binning sorting result is within the bin3 setting range. | Binning | Out |
| 12 | Bin4 | High when the binning sorting result is within the bin4 setting range. | Binning | Out |

HANDLER/SCAN INTERFACE

| | | | | |
|----|-------------|---|------------------|-----|
| 13 | Bin5 | High when the binning sorting result is within the bin5 setting range. | Binning | Out |
| 15 | Userdefine2 | High or low when the user define2 logic conditions are met. | Compare, Binning | Out |
| 16 | Userdefine1 | High or low when the user define1 logic conditions are met. | Compare, Binning | Out |
| 19 | VEXT | External DC Voltage, acceptable range is +5V. | | In |
| 20 | Ready | High when the measurement has finished. The instrument is ready for the next trigger. | Ext trigger mode | Out |
| 21 | Bin6 | High when the binning sorting result is within the bin6 setting range. | Binning | Out |
| 22 | Low | High when the compare result is deemed LO. | Compare | Out |
| 23 | Bin7 | High when the binning sorting result is within the bin7 setting range. | Binning | Out |
| 24 | Bin8 | High when the binning sorting result is within the bin8 setting range. | Binning | Out |
| 25 | Bin Out | High when the binning sorting result is out of all the bin setting ranges. | Binning | Out |

For backwards compatibility with the GOM-802 handler interface, please see page 89.

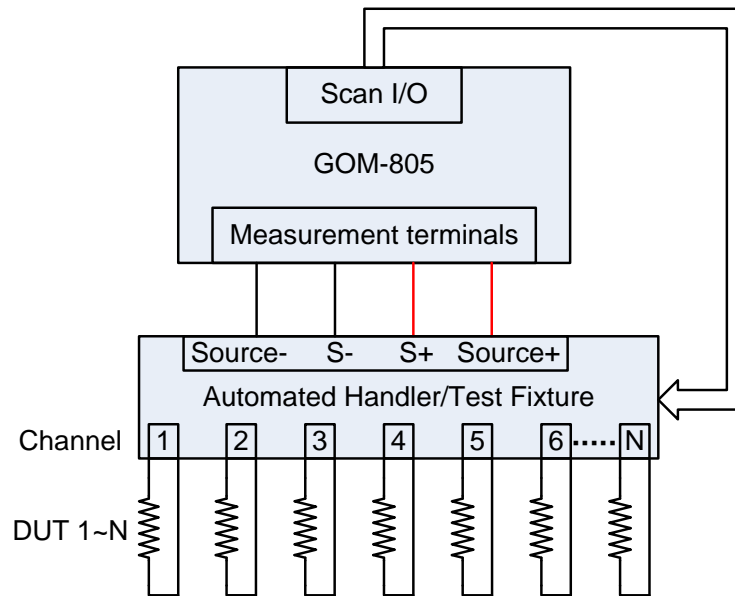
Scan Overview

| | | |
|------------------------------|--|---|
| Background | <p>The Scan function is used to automatically bin groups of up to 100 components. The associated pins in the handler interface are active when the Scan function is activated.</p> <p>There are a total of 6 outputs, 3 inputs as well as a GND and power (+5V) pin.</p> | |
| Interface and pin assignment | 25Pin D-SHELL (Female) | <p>HANDLER / SCAN / EXT I/O</p>  |
| Pin Assignment | Relay | Controls the relay output. |
| | Pass | Pass signal. Indicates the compare result is IN(pass). |
| | Low | Low signal. Indicates a LO compare result. |
| | High | High signal. Indicates a HI compare result. |
| | Clock | The clock signal will pulse high when each group of output signals (Relay, Pass, Low, High) are ready. There are up to 100 groups of output signals |
| | STRB | After all (100) output groups are ready, the STRB signal will pulse high. |

Scan Setup

Background

The Scan function sequentially scans up to 100 channels and grades the resistance of the DUT on each channel to a reference value. An automated handler or test fixture is required to interface the DUTs to the measurement terminals and the scan interface that controls the timing of each scan.



Note: The automated handler/test fixture is user-supplied. Please see your distributor for support and technical details.

Grading of each DUT is essentially the same as the compare function (page 41), the difference being the Scan function will compare up to 100 DUTs sequentially, whereas the Compare function will compare only one DUT at a time.

The scan function compares a measured value to a “Reference” value that has an upper (HI) and lower (LO) limit. If the measured value is within the upper and lower limit, then the measured value is judged as IN.

There are two modes that can be used to make a judgment: ABS and $\Delta\%$ modes.

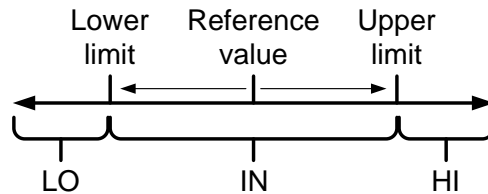
The ABS mode compares the measured value to the upper (HI) and lower (LO) limits. The upper and lower limits are set as absolute resistance values.

The $\Delta\%$ compare function compares the deviation of

the measured value from the reference value as a percentage.

$$\{ [(Measured\ Value - Reference) / Reference] \% \}.$$


A measured value that falls within the upper and lower limits is considered IN (pass), a value that falls below the lower limits is considered LO, and a value that falls over the upper limit is a HI.



For both scan modes, the IN, HI or LO will be shown on the display for each judgment (if the time between each judgment is not too fast).

Display Overview

1. Select the Scan function

Press  Scan to access the scan mode, as shown above.

2. Select the compare mode

Use the arrow keys to navigate to the Mode setting. Press the Enter key to toggle the compare mode.

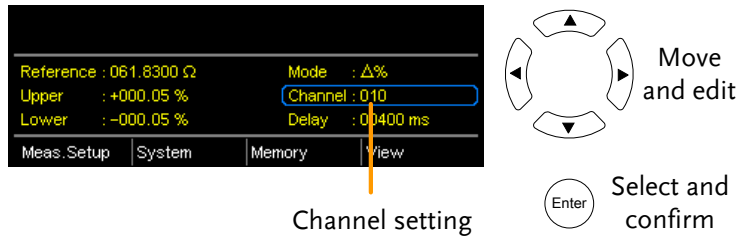
Range Abs, Δ%

3. Channel setting

The Channel setting sets the number of DUT channels that are used.

Use the arrow keys to navigate to the Channel setting and press Enter.

Use the left and right arrow keys to select a digit. Use the up and down arrow keys to edit the value of the selected digit. Press Enter to confirm the setting.



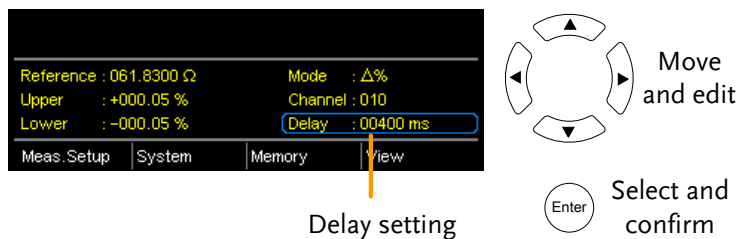
Channel Range: 01 ~100

4. Delay setting

The Delay setting adds a pause between each channel measurement.

The Use the arrow keys to navigate to the Delay setting and press Enter.

Use the left and right arrow keys to select a digit. Use the up and down arrow keys to edit the value of the selected digit. Press Enter to confirm the setting.



Delay Range: 400ms ~ 30000ms

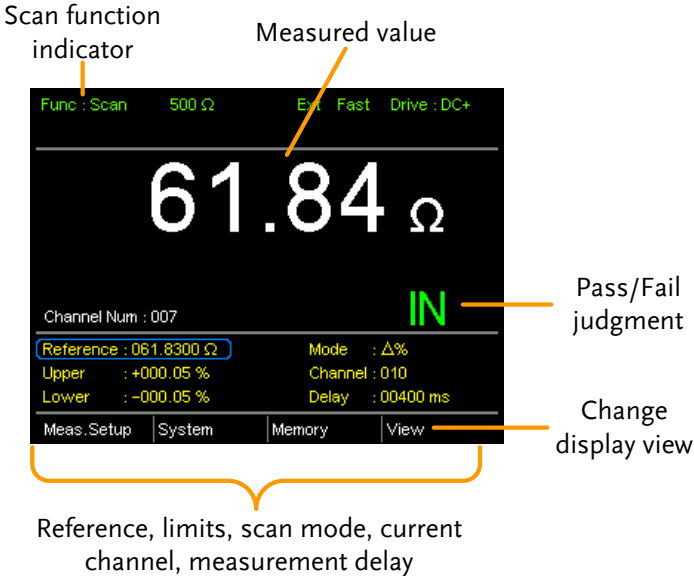
5. Start the scan. Press the **Trigger** key or input a pulse signal on the Trigger pin of the SCAN interface port to start a scan test.



Note

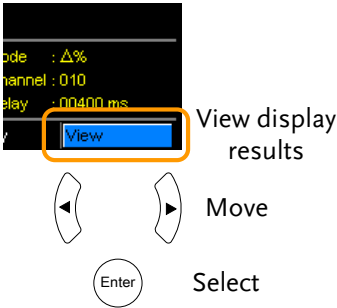
See page 64 to set the external trigger edge as a rising or falling leading edge.

The results will be displayed on the screen as each test is performed. The results will also be output through the scan port until the scan has finished.

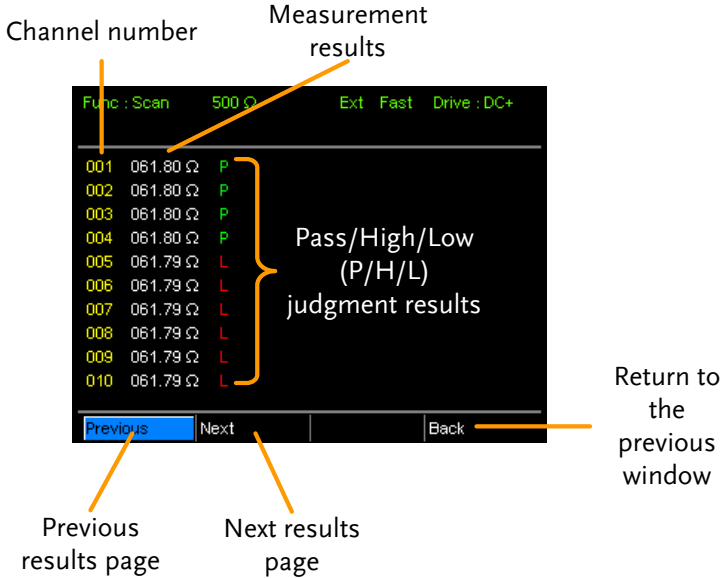


6. View Results

After the last SCAN test has finished, press the **ESC** key so that the menu system at the bottom of the display has focus. Go to View and press Enter to view the results of each channel.

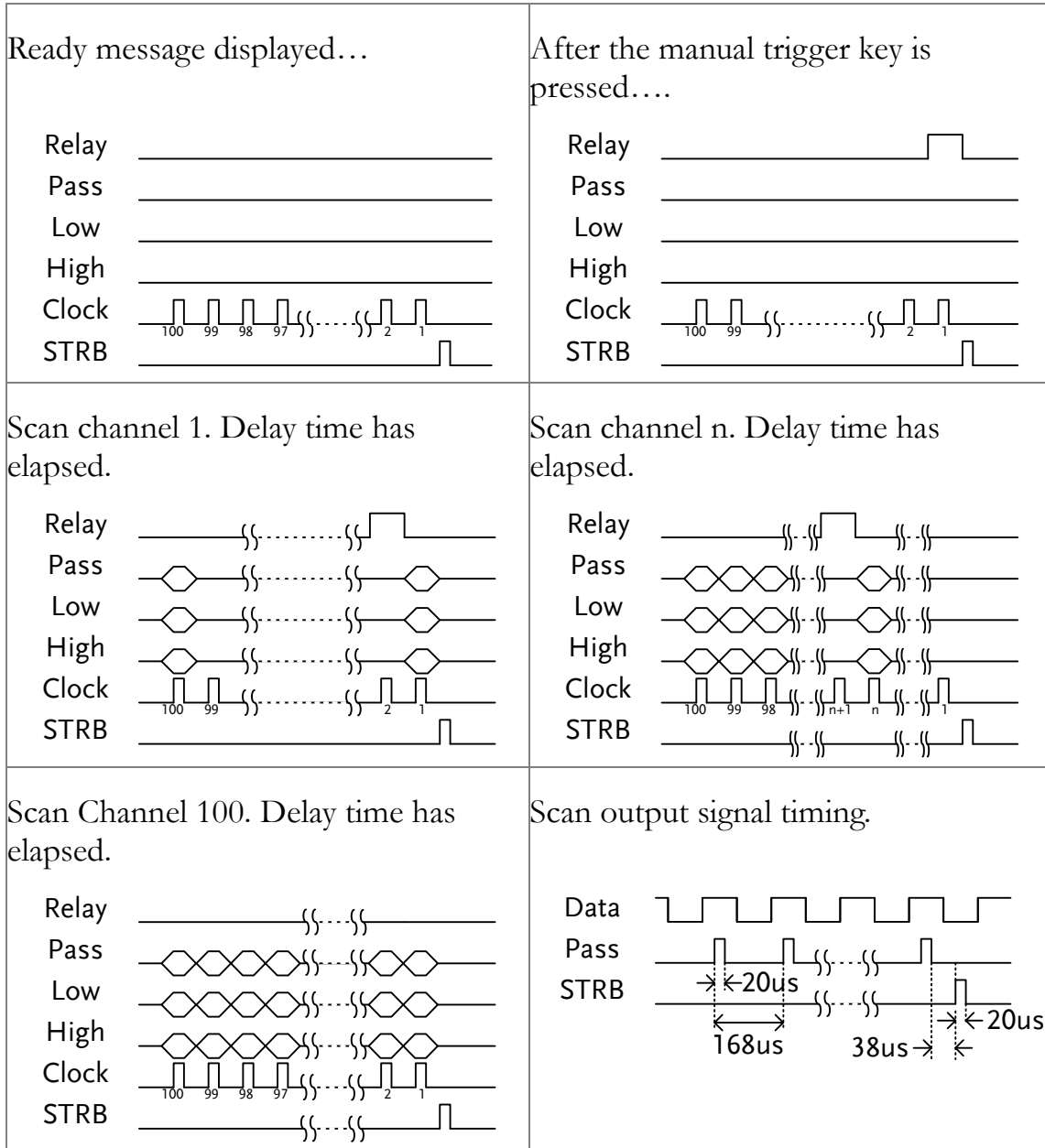


Use the Previous and Next soft-keys to view each page. Use the Back soft-key to return to the previous window.



Scan Output

Background The timing diagrams for the scan output under different conditions are shown below.



GOM-802 Compatibility for Scan and Handler Interfaces

As the handler interface on GOM-802 is a 9-pin D-sub and the GOM-805 is a 25-pin D-sub, the GOM-805 handler interface cannot be used with existing GOM-802 ATE equipment or environments without modification.

For backwards compatibility with the GOM-802 handler interface, please refer to the chart below:

GOM-805 to GOM-802 Handler/Scan Interface

| GOM-805 Handler Interface | | | GOM-802 Handler Interface | | | |
|---------------------------|-------------|----------|---------------------------|-----|---------|-------|
| Pin | Handler | Scan | | Pin | Handler | Scan |
| 1, 17 | Reserved | Reserved | | | | |
| 2 | Trigger | Trigger | → | 3 | Start | NC |
| 3, 14, 18 | GND | GND | → | 2 | GND | GND |
| 4 | Fail | High | → | 7 | Fail | High |
| 5 | High | Clock | → | 8 | High | Clock |
| 6 | Pass | Low | → | 6 | Pass | Low |
| 7 | EOT | Pass | → | 5 | EOT | Pass |
| 8 | VINT | +5V | → | 1 | +5V | +5V |
| 9 | Bin1 | | | | | |
| 10 | Bin2 | | | | | |
| 11 | Bin3 | | | | | |
| 12 | Bin4 | | | | | |
| 13 | Bin5 | | | | | |
| 15 | Userdefine2 | | | | | |
| 16 | Userdefine1 | | | | | |
| 19 | VEXT | VEXT | | | | |
| 20 | Ready | Relay | → | 4 | Ready | Relay |
| 21 | Bin6 | | | | | |
| 22 | Low | STRB | → | 9 | Low | STRB |
| 23 | Bin7 | | | | | |
| 24 | Bin8 | | | | | |
| 25 | Bin Out | | | | | |

Configure Interface

Overview The RS-232 and USB interfaces are standard for all models, however the GPIB interface is only applicable for the GOM-804G and GOM-805. The remote control interfaces allow the GOM-804/805 to be programmed for automatic testing.

For more information on remote control programming, please see the Command Overview chapter on page 102.

| | | |
|-----------|--------|--|
| Interface | USB | USB HOST |
| | RS-232 | DB-9 male port |
| | GPIB | 24 pin female GPIB port (GOM-804G, GOM-805 only) |

Configure USB Interface

Background The Type B USB port on the rear panel is used for remote control. This interface creates a virtual COM port when connected to a PC.



Note

The USB interface requires the USB driver to be installed. See page 91 to install the USB driver.

1. Connect and configure to USB.

Configure the interface to USB in System>Utility>Interface menu.

Page 71

Connect the Type A-B USB cable to the rear panel USB B port on the GOM-804/805.



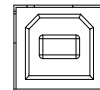
Connect the other end to the Type A port on the PC.

Install USB Driver

Background The USB driver needs to be installed when using the USB port for remote control. The USB interface creates a virtual COM port when connected to a PC.

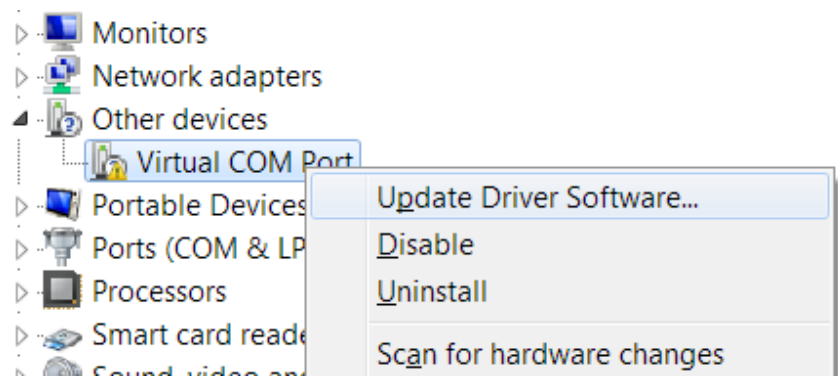
1. Select the USB driver. Configure the interface to USB in System>Utility>Interface menu. Page 71

Connect the Type A-B USB cable to the rear panel USB B port on the GOM-804/805. Connect the other end to the Type A port on the PC.



Go to the Windows Device Manager.
For Windows 7 go to:
Start Menu > Control Panel > Hardware and Sound > Device Manager

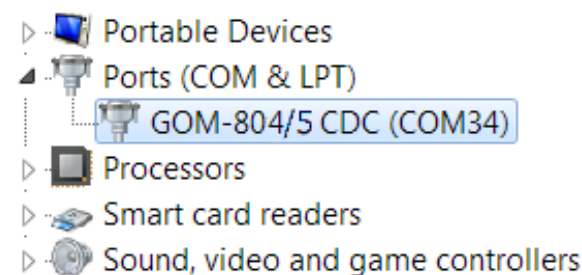
The GOM-804/805 will appear as an unknown Virtual Com Port under “Other Devices”.



Right-click Other Devices and select “Update Driver Software”.

Select “Browse my computer for driver software” and select the driver on the User Manual CD.

The GOM-805 and the COM port that it is assigned to will now appear in under the Ports (COM & LPT) node.



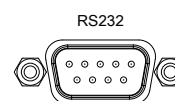
Configure RS-232 Interface

Background The GOM-804/805 can also use an RS-232C connection for remote control. When connecting to a PC ensure the correct baud rate, parity, data bits, stop bit and data control settings are used.

| | | |
|-----------------|-------------------|---|
| Settings | Baud rate | 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 |
| | Parity | None |
| | Data bits | 8 |
| | Stop bit | 1 |
| | Data flow control | None |

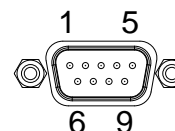
1. Select the RS-232 baud rate Configure the interface to RS232 and set the baud rate in System>Utility>Interface menu. Page 71

Connect the RS-232C cable to the rear panel RS232 port.

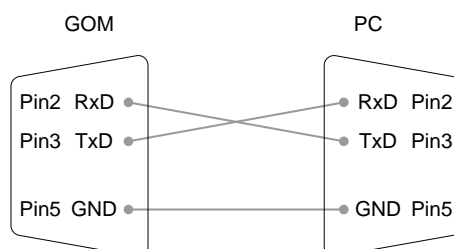


RS-232 pin assignment

Pin 2: RxD
 Pin 3: TxD
 Pin 5: GND
 Pin 1, 4, 6 ~ 9: No Connection



PC – GOM RS-232C connection The RS232C connection uses a Null-modem connection, in which transmit (TxD) and receive (RxD) lines are cross-linked.



Configure GPIB Interface

Background The GPIB interface is SCPI-1994, IEEE488.1 and IEEE488.2 compliant.



Note

The GPIB interface is only available on the GOM-804G and GOM-805.

1. Select the GPIB address

Configure the interface to GPIB and set Page 71 the GPIB address in System>Utility>Interface menu.

Connect one end of the GPIB cable to the computer and the other end to the GPIB port on the GOM-805.



RS232/USB Function Check

Operation

Invoke a terminal application such as Realterm.

For RS-232, set the COM port, baud rate, stop bit, data bit and parity accordingly.

To check the COM settings in Windows, see the Device Manager. For example, in WinXP go to the Control panel → System → Hardware tab.

Run this query from the terminal.

```
*idn?
```

This should return the Manufacturer, Model number, and Firmware version.

```
GWINSTEK,GOM805,GXXXXXXXXX,V1.00
```



Note

If you are not familiar with using a terminal application to send/receive remote commands from the serial port or via a USB connection, please page 94 (Using Realterm to Establish a Remote Connection) for more information.

Using Realterm to Establish a Remote Connection

Background Realterm is a terminal program that can be used to communicate with a device attached to the serial port of a PC or via an emulated serial port via USB.

The following instructions apply to version 2.0.0.70. Even though Realterm is used as an example to establish a remote connection, any terminal program can be used that has similar functionality.



Note

Realterm can be downloaded on Sourceforge.net free of charge.

For more information please see <http://realterm.sourceforge.net/>

1. Install Realterm Download Realterm and install according to the instructions on the Realterm website.

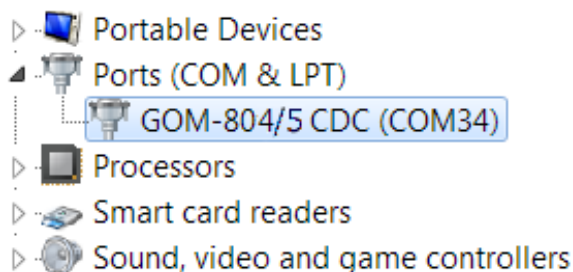
2. Configure connection Connect the GOM-804/805 via USB (page 90) or via RS232 (page 92).

If using RS232, make note of the configured baud rate.

Go to the Windows device manager and find the COM port number for the connection.

For example in Windows 7, go to the Start menu > Control Panel > Hardware and Sound > Device Manager

Double click the Ports icon to reveal the connected serial port devices and the COM port for each connected device.



If using USB, the baud rate, stop bit and parity settings can be viewed by right-clicking connected device and selecting the Properties option.

2. Run Realterm Start Realterm on the PC as an administrator.

Click:

Start menu>All Programs>RealTerm>realterm

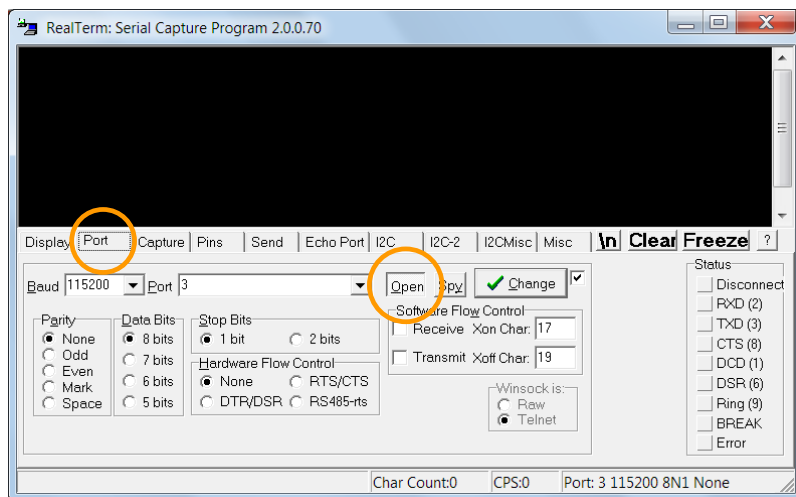
Tip: to run as an administrator, you can right click the Realterm icon in the Windows Start menu and select the Run as Administrator option.

After Realterm has started, click on the Port tab.

Enter the Baud, Parity, Data bits, Stop bits and Port number configuration for the connection.

The Hardware Flow Control and Software Flow Control options can be left at the default settings.

Press Open to connect to the GOM-804/805.



3. Test remote command

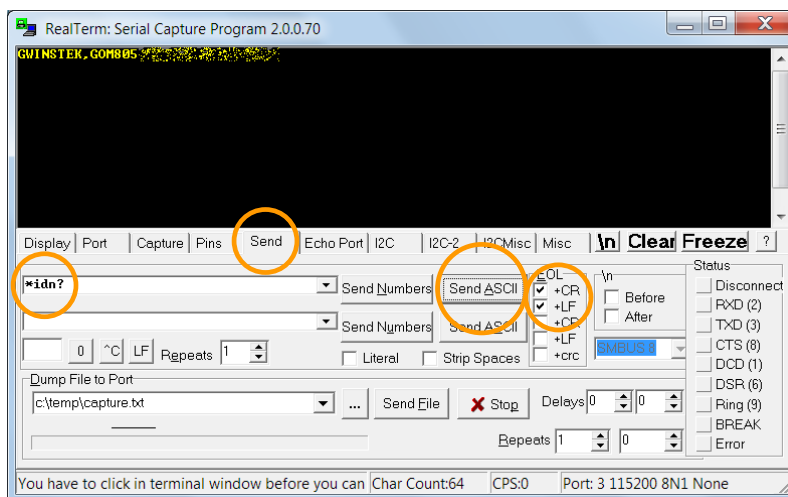
Click on the Send tab.

In the EOL configuration, check on the +CR and +LF check boxes.

Enter the query:

*:idn?

Click on Send ASCII.



The terminal display will return the following:

GWINSTEK,GOM805,GXXXXXXXXX,V1.00

(manufacturer, model, serial number, version)

4. Errors or Problems

If Realterm fails to connect to the GOM-804/805, please check all the cables and settings and try again.

GPIB Function

Background

Please use the National Instruments Measurement & Automation Controller software to confirm GPIB/LAN functionality.

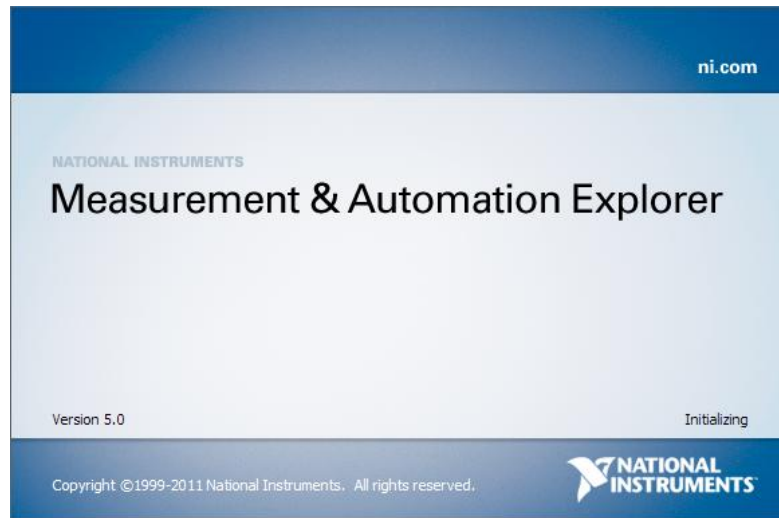
See the National Instrument website, <http://www.ni.com> for details.

1. Operation

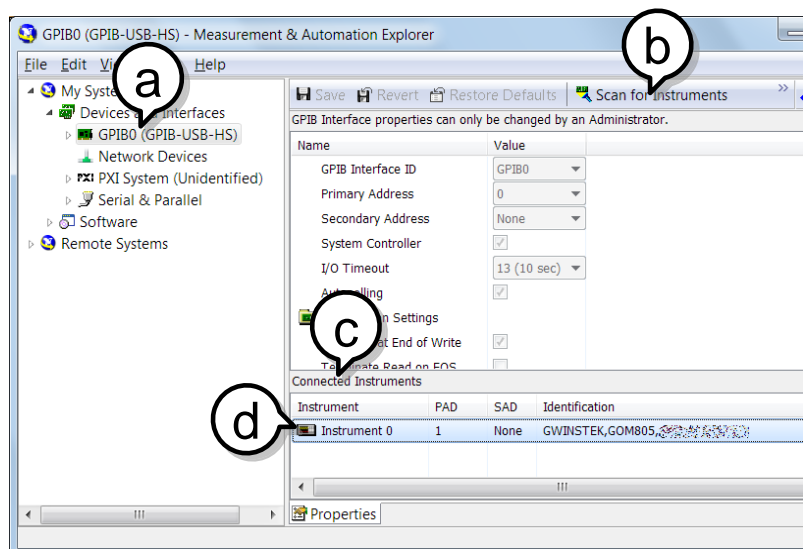
Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press:



Start>All Programs>National
Instruments>Measurement & Automation



- Step a. From the Configuration panel access;
My System>Devices and Interfaces>GPIB0
- Step b. Press the Scan for Instruments button.
- Step c. In the Connected Instruments panel the GOM-804/805 should be detected as Instrument 0 with the address the same as that configured on the unit.
- Step d. Double click the Instrument 0 icon.



- Step e. Click on the Attributes tab at the bottom.
- Step f. Click on Communicate with Instrument.

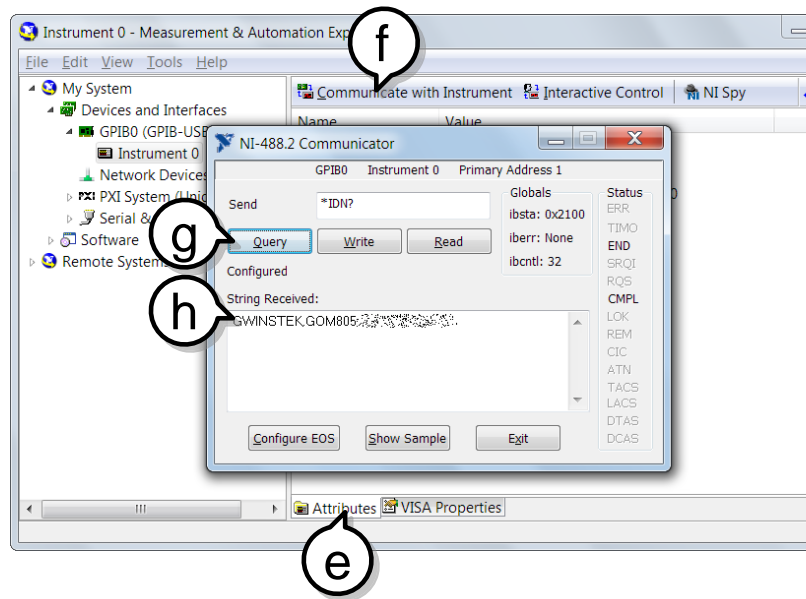
Step g. In the NI-488.2 Communicator window, ensure *IND? is written in the Send String: text box.

Click on the Query button to send the *IDN? query to the instrument.

Step h. The String Received text box will display the query return:

GWINSTEK,GOM805,GXXXXXXXXX,V1.00

(manufacturer, model, serial number, version)



The function check is complete.

SAVE/RECALL

The settings for all the major functions can be saved and recalled from 20 memory slots.

Settings can saved/recalled for the following functions:
Ohm, Compare, Binning, TC, TCONV, TEMP, Scan, Diode.

Save/Recall Settings

Background The save function saves the current function as well the settings related to that function.

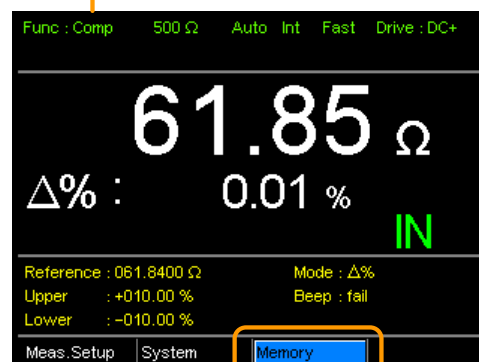
There are 20 memory slots that can be used to save and recall settings on the GOM-804/805.

1. Enter the Memory menu

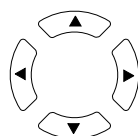
When you are in the desired function mode, press the **ESC** key (if necessary) so that the menu system at the bottom of the display has focus.

Use the arrow keys to navigate to the Memory setting and press Enter.

Function mode



Memory setting

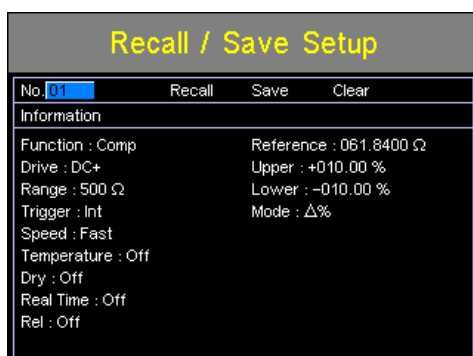


Move



Select menu or setting

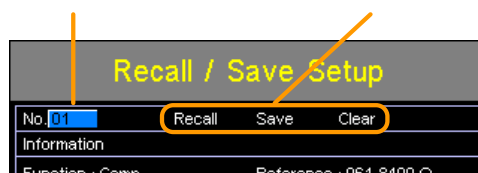
The Recall/Save Setup menu will appear.



2. Save/ Recall/Clear Memory

The No. setting should be already highlighted when entering the Recall/Save Setup menu. If not, use the Left/Right arrow keys to highlight the No. setting.

No. setting Recall, Save, Clear settings



Use the up and down arrow keys to select a memory space.

Range 01~20

*If a memory space has been used before, the settings for that memory slot will also be shown on the display.

To Save:
Use the arrow keys to go to Save and press Enter.



To Recall:
Use the arrow keys to go to Recall and press Enter.



To Clear:
Use the arrow keys to go to Clear and press Enter.



Press Enter again when asked to confirm the selected operation.

After saving the settings, press ESC to return to the current function mode.

After recalling settings, the unit will automatically go to the recalled setting function.

**Note**

Pressing ESC before pressing Enter will exit the Save/Recall/Clear operation.

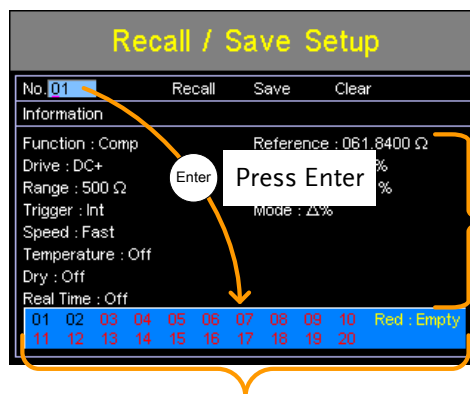
View memory slot availability

Press the Enter key when the No. setting is highlighted to see which memory slots are empty.

The status of memory slots 01 ~ 20 are shown at the bottom of the display.

Memory slots in red are empty slots while those in black have already been used.

Press Enter again to exit from this view.



Available memory slots in red.
Used memory slots in black.

**Note**

The memory number can also be selected when in the above view using the arrow keys.

COMMAND OVERVIEW

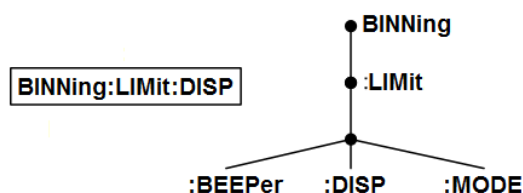
The Command overview chapter lists all the programming commands in alphabetical order. The command syntax section shows you the basic syntax rules you have to apply when using commands.

Command Syntax

| | | |
|---------------------|------------|-----------------------|
| Compatible Standard | IEEE488.2 | Partial compatibility |
| | SCPI, 1994 | Partial compatibility |

Command Structure SCPI (Standard Commands for Programmable Instruments) commands follow a tree-like structure, organized into nodes. Each level of the command tree is a node. Each keyword in an SCPI command represents each node in the command tree. Each keyword (node) of an SCPI command is separated by a colon (:).

For example, the diagram below shows an SCPI sub-structure and a command example.



Command Types There are a number of different instrument commands and queries. A command sends instructions or data to the unit and a query receives data or status information from the unit.

Command Types

Simple A single command with/without a parameter

Example SENSE:FUNCTION OHM

| | |
|---------|--|
| Query | A query is a simple or compound command followed by a question mark (?). A parameter (data) is returned. |
| Example | SENSe:RANGe? |

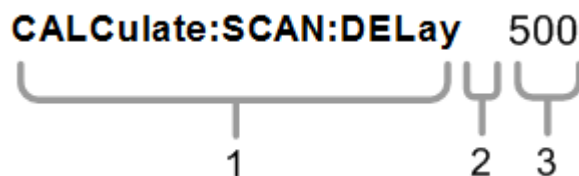
Command Forms Commands and queries have two different forms, long and short. The command syntax is written with the short form of the command in capitals and the remainder (long form) in lower case.

The commands can be written either in capitals or lower-case, just so long as the short or long forms are complete. An incomplete command will not be recognized.

Below are examples of correctly written commands.

| | |
|------------|--|
| Long form | CALCulate:COMPare:BEEPer CACLULATE:COMPARE:BEEPER calculate:compare:beeper |
| Short form | CALC:COMP:BEEP calc:comp:beep |

Command Format



1. Command header
2. Space
3. Parameter

| Common Input Parameters | Type | Description | Example |
|-------------------------|-----------|------------------------------|----------------|
| | <Boolean> | boolean logic | 0,1 |
| | <NR1> | integers | 0,1,2,3 |
| | <NR2> | decimal numbers | 0.1,3.14,8.5 |
| | <NR3> | floating point with exponent | 4.5e-1,8.25e+1 |

| | | | |
|--------------------------|----------------|--|--|
| | <Nrf> | Any of NR1,2,3 | 1,1.5,4.5e-1 |
| | <string> | ASCII text string | TEST_NAME |
| Message Terminator (EOL) | Remote Command | Marks the end of a command line. The following messages are in accordance with IEEE488.2 standard. | |
| | | LF, CR, CR+LF, LF+CR | The most common EOL character is CR+LF |

Command List

Binning Commands

| | |
|--------------------------------|-----|
| BINNING:COUNT:CLEar | 108 |
| BINNING:COUNT:TOTal | 108 |
| BINNING:COUNT:OUT | 108 |
| BINNING<X>:COUNT:RESult | 108 |
| BINNING<X>:LIMit:LOWer | 109 |
| BINNING<X>:LIMit:UPPer | 109 |
| BINNING<X>:PERCent:LOWer | 110 |
| BINNING<X>:PERCent:UPPer | 110 |
| BINNING:LIMit:BEEPer | 111 |
| BINNING:LIMit:DISPlay | 111 |
| BINNING:LIMit:MODE | 111 |
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BINNING Commands

BINNING:COUNT:CLEAr

Description Clear all bin sorting function test result counts.

Syntax BINNING:COUNT:CLEAr

Parameter/ <None>

BINNING:COUNT:TOTal

Description Returns the total number (count total) of test bin results.

Query Syntax BINNING:COUNT:TOTal?

Return parameter <NR1> 0~999999999

Example BINN:COUN:TOT?
>150
Indicates that the total number (count total) of test results (pass and fail) is 150.

BINNING:COUNT:OUT

Description Returns the number of failed (judged OUT) test results for the bin sorting function test.

Query Syntax BINNING:COUNT:OUT?

Return parameter <NR1> 0~999999999

Example BINN:COUN:OUT?
>50
Indicates that the number of failed test results is 50.

BINNING<X>:COUNT:RESult

Description Returns the number of passed (judged IN) test results for the selected bin.

Query Syntax BINNING<X>:COUNT:RESult?


Parameter <X> 1~8

| | | |
|------------------|---|------------|
| Return parameter | <NR1> | 0~99999999 |
| Example | BINN1:COUN:RES? >100 Indicates that bin1 has a pass count of 100. | |

BINNing<X>:LIMit:LOWer



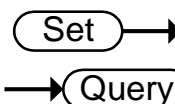

| | | |
|------------------|--|--|
| Description | Sets or returns the lower limit value (absolute value) for the selected bin. | |
| Syntax | BINNing<X>:LIMit:LOWer {<NRf>[,<String>]} | |
| Query Syntax | BINNing<X>:LIMit:LOWer? | |
| Parameter | <X> | 1~8 |
| | <NRf> | 000.0000~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If the unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0000~999.9999E±X |
| Example | BINN1:LIM:LOW 23.8,kohm Sets the bin1 lower limit value to 23.8kΩ. BINN1:LIM:LOW? >23.8000E+3 Returns the lower limit as 23.8kΩ. | |

BINNing<X>:LIMit:UPPer




| | | |
|------------------|--|--|
| Description | Sets or returns the upper limit value (absolute value) for the selected bin. | |
| Syntax | BINNing<X>:LIMit:UPPer {<NRf>[,<String>]} | |
| Query Syntax | BINNing<X>:LIMit:UPPer? | |
| Parameter | <X> | 1~8 |
| | <NRf> | 000.0000~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If the unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0000~999.9999E±X |

Example BINN1:LIM:UPP 0.95,maohm
 Sets bin1 upper limit value to 0.95MΩ.
 BINN1:LIM:UPP?
 >0.9500E+6
 Returns the upper limit as 0.95MΩ.



BINNING<X>:PERCENT:LOWer

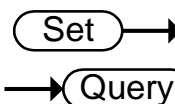
Description Sets or returns the lower value percentage value for the selected bin. The value is a percentage offset from the reference value.

Syntax BINNING<X>:PERCENT:LOWer <NRf>
 Query Syntax BINNING<X>:PERCENT:LOWer?

| | | |
|-----------|-------|---------------|
| Parameter | <X> | 1~8 |
| | <NRf> | 000.00~999.99 |

| | | |
|------------------|-------|---------------|
| Return parameter | <NR2> | 000.00~999.99 |
|------------------|-------|---------------|

Example BINN1:PERC:LOW 10.15
 Sets the bin1 lower limit percent value to -10.15%.
 BINN1: PERC:LOW?
 >10.15
 Returns the lower limit percentage value as -10.15%.



BINNING<X>:PERCENT:UPPer

Description Sets or returns the upper value percentage value for the selected bin. The value is a percentage offset from the reference value.

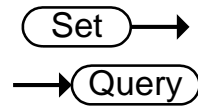
Syntax BINNING<X>:PERCENT:UPPer <NRf>
 Query Syntax BINNING<X>:PERCENT:UPPer?

| | | |
|-----------|-------|---------------|
| Parameter | <X> | 1~8 |
| | <NRf> | 000.00~999.99 |

| | | |
|------------------|-------|---------------|
| Return parameter | <NR2> | 000.00~999.99 |
|------------------|-------|---------------|

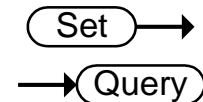
Example BINN1:PERC:UPP 150.95
 Sets the bin1 upper limit percent value to +150.95%.
 BINN1:LIM:UPP?
 >150.95
 Returns the upper limit percentage value as +150.95%.

BINNING:LIMit:BEEPer



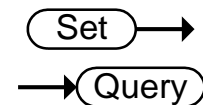
| | | |
|--------------------------------|---|--|
| Description | Sets or returns beeper mode for the bin sorting function. | |
| Syntax | BINNING:LIMit:BEEPer {OFF PASS FAIL} | |
| Query Syntax | BINNING:LIMit:BEEPer? | |
| Parameter/ Return parameter | OFF | Turns the beeper off. |
| | PASS | The beeper will sound on a pass test result. |
| | FAIL | The beeper will sound on a fail test result. |
| Example | BINN:LIM:BEEP OFF Turns the beeper off. | |

BINNING:LIMit:DISPlay



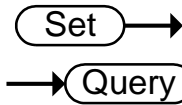
| | | |
|--------------------------------|--|-------------------------------------|
| Description | Sets or returns the bin sorting function display mode. | |
| Syntax | BINNING:LIMit:DISPlay {COMP COUNT} | |
| Query Syntax | BINNING:LIMit:DISPlay? | |
| Parameter/ Return parameter | COMP | The display is set to compare mode. |
| | COUNT | The display is set to count mode. |
| Example | BINN:LIM:DISP COMP Sets the bin sorting function display mode to compare. | |

BINNING:LIMit:MODE



| | | |
|--------------------------------|--|---|
| Description | Sets or returns the setting mode for upper and lower limits (absolute or $\Delta\%$). | |
| Syntax | BINNING:LIMit:MODE {ABS DPER} | |
| Query Syntax | BINNING:LIMit:DISP? | |
| Parameter/ Return parameter | ABS | The test results are judged from absolute values. |
| | DPER | The test results are judged from a reference value \pm a percentage offset. (delta percent) |

Example BINN:LIM:DISP DPER
Sets the mode to Δ %.



BINNING:LIMIT:REFERENCE

Description Sets or returns the limit reference value for the bin sorting function.

Syntax BINNING<X>:LIMIT:REFERENCE {<NRf>[,<String>]}
Query Syntax BINNING<X>:LIMIT:REFERENCE?

| | | |
|-----------|----------|--|
| Parameter | <NRf> | 000.0001~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If the unit is not set, the unit will be automatically set by the present range. |

| | | |
|------------------|-------|----------------------|
| Return parameter | <NR3> | 000.0001~999.9999E±X |
|------------------|-------|----------------------|

Example BINN:LIM:REF 100
Sets the limit reference value to 100Ω.
BINN:LIM:REF?
>100.0000E+0
Returns the reference as 100Ω.

BINNING:LIMIT:RESULT



Description Returns the bin sorting function test result.

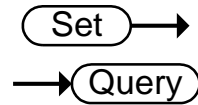
Query Syntax BINNING:LIMIT:RESULT?

| | | |
|------------------|-------|------------------------------|
| Return parameter | <NR1> | 1~8: Bin1~Bin8 9: Bin Out |
|------------------|-------|------------------------------|

Example BINN:LIMIT:RES?
>1
Indicates a pass for bin1.

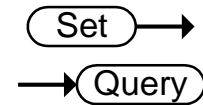
Calculate Commands

CALCulate:COMPare:BEEPer



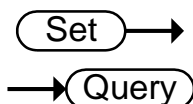
| | | |
|--------------------------------|---|--|
| Description | Sets or returns the compare function beeper mode. | |
| Syntax | CALCulate:COMPare:BEEPer {OFF PASS FAIL} | |
| Query Syntax | CALCulate:COMPare:BEEPer? | |
| Parameter/ Return parameter | OFF | Turns the beeper off. |
| | PASS | The beeper will sound on a pass test result. |
| | FAIL | The beeper will sound on a fail test result. |
| Example | CALC:COMP:BEEP FAIL Sets the beeper on when the test result is a fail. | |

CALCulate:COMPare:LIMit:LOWer



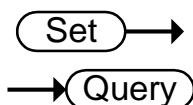
| | | |
|------------------|--|--|
| Description | Sets or returns the lower limit value for the compare function. | |
| Syntax | CALCulate:COMPare:LIMit:LOWer {<NRf>[,<String>]} | |
| Query Syntax | CALCulate:COMPare:LIMit:LOWer? | |
| Parameter | <NRf> | 000.0000~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If the unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0000~999.9999E±X |
| Example | CALC:COMP:LIM:LOW 0.123,maohm Sets the lower limit value to 0.123MΩ. CALC:COMP:LIM:LOW? >0.1230E+6 Returns the lower limit as 0.123MΩ. | |

CALCulate:COMPare:LIMit:MODE



| | | |
|--------------------------------|--|--|
| Description | Sets or returns the compare mode for the compare function. | |
| Syntax | CALCulate:COMPare:LIMit:MODE {ABS DPER PER} | |
| Query Syntax | CALCulate:COMPare:LIMit:MODE? | |
| Parameter/ Return parameter | ABS | The test results are judged from absolute values. |
| | DPER | The test results are judged from a reference value \pm a percentage offset. (delta percentage) |
| | PER | The test results are displayed as a percentage of the reference value. |
| Example | CALC:COMP:LIM:MODE ABS Sets test results as absolute values for the compare function. | |

CALCulate:COMPare:LIMit:REFERENCE



| | | |
|------------------|--|--|
| Description | Sets or returns the limit reference value for the compare function. | |
| Syntax | CALCulate:COMPare:LIMit:REF {<NRf>[,<String>]} | |
| Query Syntax | CALCulate:COMPare:LIMit:REF? | |
| parameter | <NRf> | 000.0001~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0001~999.9999E \pm X |
| Example | CALC:COMP:LIM:REF 10.00,mohm Sets the limit reference value to 10.00m Ω . CALC:COMP:LIM:REF? >10.0000E-3 Returns the limit as 10.00m Ω . | |

CALCulate:COMPare:LIMit:RESult → Query

| | | |
|------------------|--|-------------------------|
| Description | Returns the compare function test result. | |
| Query Syntax | CALCulate:COMPare:LIMit:RESult? | |
| Return parameter | <NR1> | 0: LO 1: IN 2: HI |
| Example | BINN:LIMit:RES? >2 Indicates that the test result is HI. | |

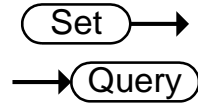
CALCulate:COMPare:LIMit:UPPer Set →
→ Query

| | | |
|------------------|--|--|
| Description | Sets or returns the upper limit value for the compare function. | |
| Syntax | CALCulate:COMPare:LIMit:UPPer {<NRf>[,<String>]} | |
| Query Syntax | CALCulate:COMPare:LIMit:UPPer? | |
| Parameter | <NRf> | 000.0000~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0000~999.9999E±X |
| Example | CALC:COMP:LIM:UPP 0.95,kohm Sets the upper limit value to 0.95kΩ. CALC:COMP:LIM:UPP? >0.9500E+3 Returns the upper limit as 0.95kΩ. | |

CALCulate:COMPare:MATH:DATA → Query

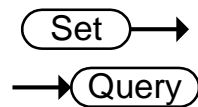
| | | |
|------------------|--|--------------------|
| Description | Returns the deviation value for the compare function. | |
| Query Syntax | CALCulate:COMPare:MATH:DATA? | |
| Return parameter | <NR3> | ±0.0000~9.9999E±X. |
| Example | CALC:COMP:MATH:DAT? >+0.3658E+2 Returns the deviation as 36.58%. | |

CALCulate:COMPare:PERCent:LOWer



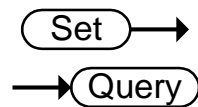
| | | |
|------------------|--|---------------|
| Description | Sets or returns the lower limit percent value for the compare function. | |
| Syntax | CALCulate:COMPare:PERCent:LOWer <NRf> | |
| Query Syntax | CALCulate:COMPare:PERCent:LOWer? | |
| Parameter | <NRf> | 000.00~999.99 |
| Return parameter | <NR2> | 000.00~999.99 |
| Example | CALC:COMP:PERC:LOW 10.00 Sets the lower limit percent value to -10.00%. CALC:COMP:PERC:LOW? >10.00 Returns the lower limit as -10.00%. | |

CALCulate:COMPare:PERCent:UPPer



| | | |
|------------------|--|---------------|
| Description | Sets or returns the upper limit percent value for the compare function. | |
| Syntax | CALCulate:COMPare:PERCent:UPPer <NRf> | |
| Query Syntax | CALCulate:COMPare:PERCent:UPPer? | |
| Parameter | <NRf> | 000.00~999.99 |
| Return parameter | <NR2> | 000.00~999.99 |
| Example | CALC:COMP:PERC:UPP 90.00 Sets the upper limit percent value to +90.00%. CALC:COMP:PERC:UPP? >90.00 Returns the upper limit as +90.00%. | |

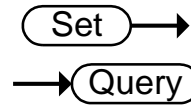
CALCulate:SCAN:CHANnel



| | | |
|--------------------------------|--|-------|
| Description | Sets or returns the channel for the scan function. | |
| Syntax | CALCulate:SCAN:CHANnel <NR1> | |
| Query Syntax | CALCulate:SCAN:CHANnel? | |
| Parameter/ Return parameter | <NR1> | 1~100 |

Example `CALC:SCAN:CHAN 5`
 Sets the channel to 5.

CALCulate:SCAN:DELAy



Description Sets or returns the interval delay for the scan function.

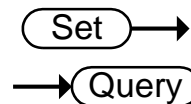
Syntax `CALCulate:SCAN:DELAy <NR1>`

Query Syntax `CALCulate:SCAN:DELAy?`

| | | |
|--------------------------------|--------------------------|----------------------|
| Parameter/ Return parameter | <code><NR1></code> | 400~30000 Unit:ms |
|--------------------------------|--------------------------|----------------------|

Example `CALC:SCAN:DEL 500`
 Sets interval delay of the scan to 500ms.

CALCulate:SCAN:LIMit:LOWer



Description Sets or returns the lower limit value for the scan function.

Syntax `CALCulate:SCAN:LIMit:LOWer {<NRf>[,<String>]}`

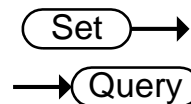
Query Syntax `CALCulate:SCAN:LIMit:LOWer?`

| | | |
|-----------|-----------------------------|--|
| Parameter | <code><NRf></code> | 000.0000~999.9999 |
| | <code><String></code> | mohm/ohm/kohm/maohm,unit If unit is not set, the unit will be automatically set by the present range. |

| | | |
|------------------|--------------------------|----------------------|
| Return parameter | <code><NR3></code> | 000.0000~999.9999E±X |
|------------------|--------------------------|----------------------|

Example `CALC:SCAN:LIM:LOW 0.123,maohm`
 Sets the lower limit value to 0.123MΩ.
`CALC:SCAN:LIM:LOW?`
`>0.1230E+6`
 Returns the lower limit as 0.123MΩ.

CALCulate:SCAN:LIMit:MODE



Description Sets or returns the scan function compare mode.

Syntax `CALCulate:SCAN:LIMit:MODE {ABS|DPER}`

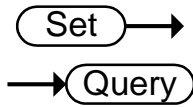
Query Syntax `CALCulate:SCAN:LIMit:MODE?`

| | | |
|--------------------------------|-----|---|
| Parameter/ Return parameter | ABS | The test results are judged from absolute values. |
|--------------------------------|-----|---|

| | | |
|--|------|---|
| | DPER | The test results are judged from a reference value \pm a percentage offset. (delta percent) |
|--|------|---|

Example CALC:SCAN:LIM:MODE ABS
Sets compare mode to absolute values.

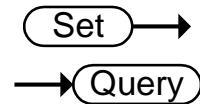
CALCulate:SCAN:LIMit:REFErence



| | | |
|------------------|--|---|
| Description | Sets or returns the reference limit for the scan function. | |
| Syntax | CALCulate:SCAN:LIMit:REFErence {<NRf>[,<String>]} | |
| Query Syntax | CALCulate:SCAN:LIMit:REFErence? | |
| Parameter | <NRf> | 000.0001~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If unit is not set,the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0001~999.9999E \pm X |

Example CALC:SCAN:LIM:REF 10.00,mohm
Sets the reference limit to 10.00m Ω .
CALC:SCAN:LIM:REF?
>10.0000E-3
Returns the reference limit as 10.00m Ω .

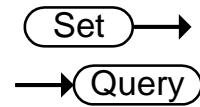
CALCulate:SCAN:LIMit:UPPer



| | | |
|------------------|---|--|
| Description | Sets or returns upper limit of the scan function. | |
| Syntax | CALCulate:SCAN:LIMit:UPPer {<NRf>[,<String>]} | |
| Query Syntax | CALCulate:SCAN:LIMit:UPPer? | |
| Parameter | <NRf> | 000.0000~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0000~999.9999E \pm X |

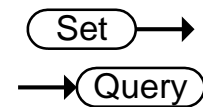
Example CALC:SCAN:LIM:UPP 1.37,kohm
Sets the upper limit to 1.37k Ω .
CALC:SCAN:LIM:UPP?
>1.3700E+3
Returns the upper limit as 1.37k Ω .

CALCulate:SCAN:PERCent:LOWer



| | | |
|------------------|--|---------------|
| Description | Sets or returns lower limit percent value for the scan function. | |
| Syntax | CALCulate:SCAN:PERCent:LOWer <NRf> | |
| Query Syntax | CALCulate:SCAN:PERCent:LOWer? | |
| Parameter | <NRf> | 000.00~999.99 |
| Return parameter | <NR2> | 000.00~999.99 |
| Example | CALC:SCAN:PERC:LOW 10.00 Sets the lower limit percent value to -10.00%. CALC:SCAN:PERC:LOW? >10.00 Returns the lower limit as -10.00%. | |

CALCulate:SCAN:PERCent:UPPer



| | | |
|------------------|--|---------------|
| Description | Sets or returns the upper limit percent value for the scan function. | |
| Syntax | CALCulate:SCAN:PERCent:UPPer <NRf> | |
| Query Syntax | CALCulate:SCAN:PERCent:UPPer? | |
| Parameter | <NRf> | 000.00~999.99 |
| Return parameter | <NR2> | 000.00~999.99 |
| Example | CALC:SCAN:PERC:UPP 90.00 Sets the upper limit percent value to +90.00%. CALC:SCAN:PERC:UPP? >90.00 Returns the upper limit as +90.00%. | |


Memory Commands

MEMory:CLEar




| | | |
|-------------|--|------|
| Description | Clears the data from the selected memory slot. | |
| Syntax | MEMory:CLEar <NR1> | |
| Parameter | <NR1> | 1~20 |
| Example | MEM:CLE 1 Clear data from memory slot 1. | |

MEMory:RECall



| | | |
|-------------|--|------|
| Description | Recalls the settings from the selected memory slot. | |
| Syntax | MEMory:RECall <NR1> | |
| Parameter | <NR1> | 1~20 |
| Example | MEM:REC 1 Recall the settings from memory slot 1. | |

MEMory:SAVe



| | | |
|-------------|---|------|
| Description | Saves the settings to the selected memory slot. | |
| Syntax | MEMory:SAVe <NR1> | |
| Parameter | <NR1> | 1~20 |
| Example | MEM:SAV 1 Saves the settings to memory slot 1. | |

MEMory:STATe



| | | |
|------------------|---|--|
| Description | Returns the status of all the memory slots. | |
| Query Syntax | MEMory:STATe? | |
| Return parameter | <String> | 23 Characters composed of “N” or “F”, where “N” indicates “Not used” and “F” indicates “Full”. |

Example

MEM:STAT?

> NFFNN-NNNNN-NNNNN-NNNNN

Indicates that memory slots 2 and 3 have data and that all other memory slots are empty.

Sense Commands

SENSE:AUTo

| | | |
|--------------------------------|--|--------------------|
| Description | Sets or returns the auto-range state. | |
| Syntax | SENSE:AUTo <NR1> {OFF ON} | |
| Query Syntax | SENSE:AUTo? | |
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Auto-Range is off. |
| | ON | Auto-Range is on. |
| Example | SENSE:AUT ON Sets auto-range mode on. | |

SENSE:DISPlay

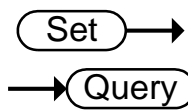
| | | |
|--------------------------------|---|-------------------------|
| Description | Sets or returns the display mode. There are two display modes, normal and simple. | |
| Syntax | SENSE:DISPlay <NR1> {OFF ON} | |
| Query Syntax | SENSE:DISPlay? | |
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Display mode is normal. |
| | ON | Display mode is simple. |
| Example | SENSE:DISP OFF Sets the display mode to normal. | |

SENSE:FUNcTion

| | | |
|--------------|--|--|
| Description | Sets or returns the function mode. | |
| Syntax | SENSE:FUNcTion {OHM COMP BIN TC TCONV SCAN DIODE} | |
| Query Syntax | SENSE:FUNcTion? | |

| | | |
|--------------------------------|-------|------------|
| Parameter/ Return parameter | OHM | OHM MODE |
| | COMP | COMP MODE |
| | BIN | BIN MODE |
| | TC | TC MODE |
| | TCONV | TCONV MODE |
| | SCAN | SCAN MODE |
| | DIODE | DIODE MODE |

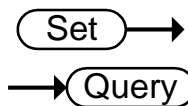
Example SENS:FUNC OHM
Sets ohm mode on.



SENSe:RANGe

| | | |
|------------------|--|-------------|
| Description | Sets or returns the range of the present function. | |
| Syntax | SENSe:RANGe <NRf> | |
| Query Syntax | SENSe:RANGe? | |
| Parameter | <NRf> | 5E-2 ~ 5E+6 |
| Return parameter | <NR3> | 5E-2 ~ 5E+6 |

Example SENS:RANG 0.05
Sets range to 50mΩ.
SENS:RANG?
>5.0000E-2
Returns the range as 50mΩ.

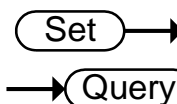


SENSe:SPEed

| | | |
|--------------------------------|--|----------------------------|
| Description | Sets or returns the measurement speed. | |
| Syntax | SENSe:SPEed {SLOW FAST} | |
| Query Syntax | SENSe:SPEed? | |
| Parameter/ Return parameter | SLOW | Measurement speed is slow. |
| | FAST | Measurement speed is fast. |

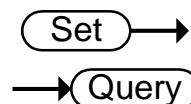
Example SENS:SPE FAST
Sets measurement speed to the fast rate.

SENSe:REL:DATA



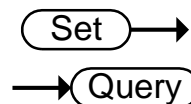
| | | |
|------------------|---|--|
| Description | Sets or returns the relative value for the relative function. | |
| Syntax | SENSe:REL:DATA <NRf> | |
| Query Syntax | SENSe:REL:DATA? | |
| Parameter | <NRf> | 0.0000~500.00 The unit will be auto set by the present range. |
| Return parameter | <NR3> | ±0.0000~5.1000E±X |
| Example | SENS:REL:DAT 490.32 Sets the relative function value to 490.32Ω. SENS:REL:DAT? >4.9032E+2 Returns the relative value (490.32Ω). | |

SENSe:REL:STATE



| | | |
|--------------------------------|--|---------------------------------|
| Description | Sets or returns the relative function state. | |
| Syntax | SENSe:REL:STATE <NR1> {OFF ON} | |
| Query Syntax | SENSe:REL:STATE? | |
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Turn the relative function off. |
| | ON | Turn the relative function on. |
| Example | SENS:REL:STAT OFF Sets the relative function off. | |

SENSe:REALtime:STATE



| | | |
|--------------|---|--|
| Description | Sets or returns the real time function state. | |
| Syntax | SENSe:REALtime:STATE <NR1> {OFF ON} | |
| Query Syntax | SENSe:REALtime:STATE? | |

| | | |
|--------------------------------|-------|----------------------------------|
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Turn the real time function off. |
| | ON | Turn the real time function on. |

Example SENS:REAL:STAT ON
 Turns the real time function on.

Source Commands

SOURce:DRY

| | | |
|--------------------------------|--|---------------------------------|
| Description | Sets or returns the dry circuit test mode. | |
| Syntax | SOURce:DRY {<NR1> {OFF ON}} | |
| Query Syntax | SOURce:DRY? | |
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Turn dry circuit test mode off. |
| | ON | Turn dry circuit test mode on. |
| Example | SOUR:DRY On Turns the dry circuit test mode on. | |

SOURce:DRIVE

| | | |
|--------------------------------|---|--------------------|
| Description | Sets or returns the drive mode. | |
| Syntax | SOURce:DRIVE <NR1> | |
| Query Syntax | SOURce:DRIVE? | |
| Parameter/ Return parameter | <NR1> | 1: the DC+ mode. |
| | | 2: the DC- mode. |
| | | 3: the PULSE mode. |
| | | 4: the PWM mode. |
| | | 5: the ZERO mode. |
| Example | SOURce:DRIVE 3 Sets the drive mode to pulse. | |

Status Commands

STATus:PRESet

Set →

| | |
|-------------|--|
| Description | Sets the QUESTionable enable register to zero. |
| Syntax | STATus:PRESet <NONE> |
| Parameter | <None> |

STATus:QUESTionable:ENABLE

Set →

→ Query

| | |
|--------------------------------|--|
| Description | Sets or returns the Questionable Data Enable register. |
| Syntax | STATus:QUESTionable:ENABLE <NR1> |
| Query Syntax | STATus:QUESTionable:ENABLE? |
| Parameter/ Return parameter | <NR1> 0~32767. |

Example
 STAT:QUES:ENAB 2560
 Sets the Questionable Data Enable register to 0001010000000000.

STATus:QUESTionable:EVENT

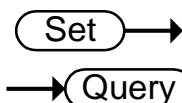
→ Query

| | |
|------------------|---|
| Description | Returns the contents of the Questionable Data Event register. |
| Query Syntax | STATus:QUESTionable:EVENT? |
| Return parameter | <NR1> 0~32767 |

Example
 STAT:QUES:EVENT?
 >512
 512 indicates that the Questionable Data Event register=0000001000000000.

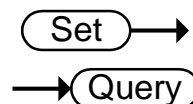
System Commands

SYSTem:AVERage:DATa



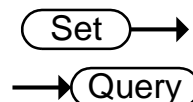
| | | |
|--------------------------------|---|------|
| Description | Sets or returns the number of measurements used for the average function. | |
| Syntax | SYSTem:AVERage:DATa <NR1> | |
| Query Syntax | SYSTem:AVERage:DATa? | |
| Parameter/ Return parameter | <NR1> | 2~10 |
| Example | SYST:AVER:DAT 5 5 measurements are used to perform the average function. | |

SYSTem:AVERage:STATe



| | | |
|--------------------------------|---|--------------------------------|
| Description | Sets or returns the average function state. | |
| Syntax | SYSTem:AVERage:STATe <NR1> {OFF ON} | |
| Query Syntax | SYSTem:AVERage:STATe? | |
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Turn the average function off. |
| | ON | Turn the average function on. |
| Example | SYST:AVER:STAT OFF Turns the average function off. | |

SYSTem:BRIGhtness



| | | |
|--------------------------------|---------------------------------------|------------------|
| Description | Sets or returns the brightness level. | |
| Syntax | SYSTem:BRIGhtness <NR1> | |
| Query Syntax | SYSTem:BRIGhtness? | |
| Parameter/ Return parameter | <NR1> | 1(dim)~5(bright) |

Example SYST:BRIG 4
Turns the brightness level to 4.

SYSTEM:ERRor → Query

| | |
|------------------|--|
| Description | Returns the current system error, if any. |
| Query Syntax | SYSTEM:ERRor? |
| Return parameter | <String> Error number,"Error message" |
| Example | SYST:ERR? >0,"No error". Indicates that there is no error message. |

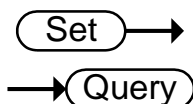
SYSTEM:HANDler Set →
→ Query

| | |
|--------------------------------|---|
| Description | Sets or returns the handler state. |
| Syntax | SYSTEM:HANDler {CLEAR HOLD} |
| Query Syntax | SYSTEM:HANDler? |
| Parameter/ Return parameter | Clear It clears the last result before executing measurement. HOLD It holds the test result and changes when a different result appears. |
| Example | SYST:HAND HOLD Sets the test result to the hold state. |

SYSTEM:KEYClick:BEEPer Set →
→ Query

| | |
|--------------------------------|---|
| Description | Sets or returns the keyclick beeper state. |
| Syntax | SYSTEM:KEYClick:BEEPer <NR1> {OFF ON} |
| Query Syntax | SYSTEM:KEYClick:BEEPer? |
| Parameter/ Return parameter | <NR1> 0:OFF. 1:ON. OFF Turn the keyclick beeper off. ON Turn the keyclick beeper on. |
| Example | SYST:KEYC:BEEP OFF Sets the keyclick beeper off. |

SYSTem:LFRequency



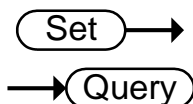
| | | |
|--------------------------------|---|--|
| Description | Sets or returns the frequency setting for the line filter. | |
| Syntax | SYSTem:LFRequency {AUTO 50 60} | |
| Query Syntax | SYSTem:LFRequency? | |
| Parameter/ Return parameter | AUTO | The frequency setting for the line filter is automatically detected. |
| | 50 | The frequency is 50Hz. |
| | 60 | The frequency is 60Hz. |
| Example | <p>SYST:LFR 60 Sets the line frequency to 60Hz.</p> <p>SYST:LFR? >60Hz Returns the line frequency as 60Hz.</p> | |

SYSTem:LOCAl



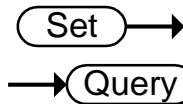
| | | |
|-------------|--|--|
| Description | Enables local control (front panel control) and disables remote control. | |
| Syntax | SYSTem:LOCAl | |
| Parameter | <None> | |

SYSTem:MDELaY:DATA



| | | |
|--------------------------------|---|--|
| Description | Sets or returns the measurement delay time. | |
| Syntax | SYSTem:MDELaY:DATA <NRf> | |
| Query Syntax | SYSTem:MDELaY:DATA? | |
| Parameter/ Return parameter | <NRf> | 0.000~100.000 |
| | | Unit:ms For values under 1s, the unit resolution is 1ms. For values above 1s, the unit resolution is 0.1s. |

Example SYST:MDEL:DAT 1.105
 Sets the delay time of measure is 1.1s.
 SYST:MDEL:DAT?
 >001.100
 Returns the measurement delay as 1.1s.



SYSTem:MDELaY:STATe

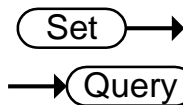
Description Sets or returns the measurement delay function state.

Syntax SYSTem:MDELaY:STATe <NR1> | {OFF|ON}

Query Syntax SYSTem:MDELaY:STATe?


| | | |
|--------------------------------|-------|---------------------------------|
| Parameter/ Return parameter | <NR1> | 0:OFF. 1:ON. |
| | OFF | Turn the measurement delay off. |
| | ON | Turn the measurement delay on. |

Example SYST:MDEL:STAT OFF
 Turns the measurement delay function off.



SYSTem:PWM:ON

Description Sets or returns the duty ON period for the PWM drive mode.

 Note PWM drive mode is only available for the GOM-805.

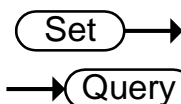
Syntax SYSTem:PWM:ON <NR1>

Query Syntax SYSTem:PWM:ON?

| | | |
|--------------------------------|-------|--|
| Parameter/ Return parameter | <NR1> | 3~99 Unit: time units. For 60Hz LF, each unit is equal 16.6ms. For 50Hz LF, each unit is equal to 20.0ms. |
|--------------------------------|-------|--|

Example SYST:PWM:ON 5
 Sets the duty ON time to 5 adc units.

SYSTem:PWM:OFF



| | | |
|--------------------------------|---|---------------------|
| Description | Sets or returns the duty OFF period for the PWM drive mode. | |
| Syntax | SYSTem:PWM:OFF <NR1> | |
| Query Syntax | SYSTem:PWM:OFF? | |
| Parameter/ Return parameter | <NR1> | 100~9999 Unit:ms |
| Example | SYST:PWM:OFF 200 Sets the duty OFF period to 200 ms. | |

SYSTem:SERial





| | | |
|------------------|----------------------------|--------------|
| Description | Returns the serial number. | |
| Query Syntax | SYSTem:SERial? | |
| Return parameter | <String> | 9 characters |
| Example | SYST:SER? > GXXXXXXXX | |


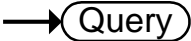
SYSTem:VERSion



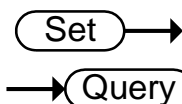
| | | |
|------------------|--|---------------|
| Description | Returns the SCPI version of the device. | |
| Query Syntax | SYSTem:VERSion? | |
| Return parameter | <String> | 10 characters |
| Example | SYST:VERS? >SCPI1994.0. SCPI version: 1994 | |

Temperature Commands

| TEMPerature:AMBient:DATA | |
|--------------------------|--|
| |   |
| Description | Sets or returns the user-set ambient temperature value for the temperature compensation and the temperature conversion function. |
| Syntax | TEMPerature:AMBient:DATA <NRf> |
| Query Syntax | TEMPerature:AMBient:DATA? |
| Parameter | <NRf> -50.0~399.9 (Unit: °C) |
| Return parameter | <NR2> -50.0~399.9 (Unit: °C) |
| Example | TEMP:AMB:DAT 25.6 Sets the user ambient temperature value to +25.6°C. TEMP:AMB:DAT? >25.6 Returns the set ambient temperature as 25.6°C. |

| TEMPerature:AMBient:STATe | | | | | | | |
|--------------------------------|---|-------|-----------------|-----|--|----|---|
| |   | | | | | | |
| Description | Sets or returns the state of the user-set ambient temperature. | | | | | | |
| Syntax | TEMPerature:AMBient:STATe <NR1> {OFF ON} | | | | | | |
| Query Syntax | TEMPerature:AMBient:STATe? | | | | | | |
| Parameter/ Return parameter | <table border="1"> <tr> <td><NR1></td> <td>0:OFF. 1:ON.</td> </tr> <tr> <td>OFF</td> <td>Disables the user-set ambient temperature.</td> </tr> <tr> <td>ON</td> <td>Enables the user-set ambient temperature.</td> </tr> </table> | <NR1> | 0:OFF. 1:ON. | OFF | Disables the user-set ambient temperature. | ON | Enables the user-set ambient temperature. |
| <NR1> | 0:OFF. 1:ON. | | | | | | |
| OFF | Disables the user-set ambient temperature. | | | | | | |
| ON | Enables the user-set ambient temperature. | | | | | | |
| Example | TEMP:AMB:STAT OFF Disables the user-set ambient temperature. | | | | | | |

TEMPerature:COMPensate:COEFFicient



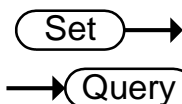
Description Sets or returns the temperature coefficient for temperature compensation function.

Syntax TEMPERATURE:COMPensate:COEFFicient <NR1>
Query Syntax TEMPERATURE:COMPensate:COEFFicient?

Parameter/ <NR1> -9999~+9999
Return parameter

Example TEMP:COMP:COEF 3930
 Sets the temperature coefficient to 3930ppm.

TEMPerature:COMPensate:CORRect



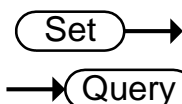
Description Sets or returns the reference temperature for the temperature compensation function.

Syntax TEMPERATURE:COMPensate:CORRect <NRf>
Query Syntax TEMPERATURE:COMPensate:CORRect?

Parameter <NRf> -50.0~399.9 (Unit: °C)
Return parameter <NR2> -50.0~399.9 (Unit: °C)

Example TEMP:COMP:CORR 25.5
 Sets the reference temperature to 25.5°C.

TEMPerature:CONVersion:CONStant



Description Sets or returns the temperature constant for the temperature conversion function.

Syntax TEMPERATURE:CONVersion:CONStant <NRf>
Query Syntax TEMPERATURE:CONVersion:CONStant?

Parameter <NRf> 0.0~999.9
Return parameter <NR2> 0.0~999.9

Example TEMP:CONV:CONS 235
 Sets the temperature constant to 235.

TEMPerature:CONVersion:DISPlay

Set →
→ Query

| | | |
|--------------------------------|---|-----------------------|
| Description | Sets or returns the temperature display mode for the temperature conversion function. | |
| Syntax | TEMPerature:CONVersion:DISPlay <NR1> | |
| Query Syntax | TEMPerature:CONVersion:DISPlay? | |
| Parameter/ Return parameter | <NR1> | 1: ΔT 2: T |
| Example | TEMP:CONV:DISP 1 Sets the temperature display mode for the temperature conversion function is ΔT . | |

TEMPerature:CONVersion:MATH:DATA

→ Query

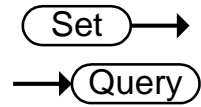
| | | |
|------------------|--|-------------------------------|
| Description | Returns conversion function deviation value. | |
| Query Syntax | TEMPerature:CONVersion:MATH:DATA? | |
| Return parameter | <NR3> | $\pm 0.000 \sim 9.999E \pm X$ |
| Example | TEMP:CONV:MATH:DAT? Returns 1.250E+2. | |

TEMPerature:CONVersion:RESistance

Set →
→ Query

| | | |
|------------------|---|--|
| Description | Sets or returns the initial resistance for the temperature conversion function. | |
| Syntax | TEMPerature:CONVersion:RESistance {<NRf>[,<String>]} | |
| Query Syntax | TEMPerature:CONVersion:RESistance? | |
| Parameter | <NRf> | 000.0001~999.9999 |
| | <String> | mohm/ohm/kohm/maohm,unit If the unit is not set, the unit will be automatically set by the present range. |
| Return parameter | <NR3> | 000.0001~999.9999E $\pm X$ |

Example TEMP:STAT ON
 Sets the temp function on.



TEMPerature:UNIT

Description Sets or returns the temperature unit. (Only used for the display readback.)

Syntax TEMPerature:UNIT {DEGC|DEGF}

Query Syntax TEMPerature:UNIT?

| | | |
|------------|------|----|
| Parameter/ | DEGC | °C |
|------------|------|----|

| | | |
|------------------|------|----|
| Return parameter | DEGF | °F |
|------------------|------|----|

Example TEMP:UNIT DEGF
 Sets temperature unit to °F (Fahrenheit).

Trigger Commands

READ

→ Query

| | | |
|------------------|--|---------------------------------|
| Description | Returns the measurement value. | |
| Query Syntax | READ? | |
| Return parameter | <NR3> | $\pm 0.0000 \sim 5.1000E \pm X$ |
| Example | READ? >+2.2012E+0 Returns the measurement. | |

MEASure<X>

→ Query

| | | |
|------------------|---|--|
| Description | Returns the results of the selected channel in the scan mode, including HI/LO/IN and value. | |
| Query Syntax | MEASure<X>? | |
| Parameter | <X> | Channel 1~100 |
| Return parameter | 0 1 2,<NR3> | 0:LO 1:IN 2:HI <NR3>: Measurement result. |
| Example | MEAS1? >1,+0.9978E+1 Returns channel 1 as 9.978Ω. | |

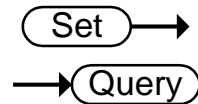
SHOW

→ Query

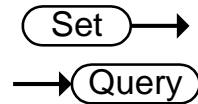
| | | |
|------------------|---|--|
| Description | Returns the judgments of all (up to 100) channels in the scan mode. | |
| Query Syntax | SHOW? | |
| Return parameter | <String> | 100 characters 0:LO 1:IN 2:HI _:Channel not active |

| | |
|---------|-------------------------------------|
| Example | SHOW? Returns 1111111111_____ |
|---------|-------------------------------------|

TRIGger:EDGE

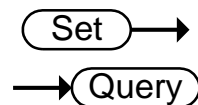


| | | |
|--------------------------------|--|-------------------------|
| Description | Sets or returns the trigger edge (falling or rising edge). | |
| Syntax | TRIGger:EDGE {RISING FALLING} | |
| Query Syntax | TRIGger:EDGE? | |
| Parameter/ Return parameter | RISING | Select rising trigger. |
| | FALLING | Select falling trigger. |
| Example | TRIG:EDGE FALLING Sets the trigger to falling edge. | |



TRIGger:DELay:DATA

| | | |
|--------------------------------|---|-------------------|
| Description | Sets or returns the trigger delay time. | |
| Syntax | TRIGger:DELay:DATA <NR1> | |
| Query Syntax | TRIGger:DELay:DATA? | |
| Parameter/ Return parameter | <NR1> | 0~1000 Unit:ms |
| | | |
| Example | TRIG:DEL:DAT 100 Sets the trigger delay time to 100ms. | |

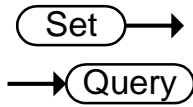


TRIGger:DELay:STATe

| | | |
|--------------------------------|---|--------------------------------------|
| Description | Sets or returns the trigger delay function state. | |
| Syntax | TRIGger:DELay:STATe <NR1> {OFF ON} | |
| Query Syntax | TRIGger:DELay:STATe? | |
| Parameter/ Return parameter | <NR1> | 0:ON 1:OFF |
| | OFF | Turn the trigger delay function off. |
| | ON | Turn the trigger delay function on. |

Example TRIG:DEL:STAT OFF
 Turns the trigger delay function off.

TRIGger:SOURce



Description Sets or returns current trigger source.

Syntax TRIGger:SOURce {INT|EXT}

Query Syntax TRIGger:SOURce?

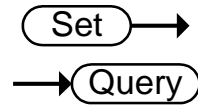
| | | |
|--------------------------------|-----|------------------------|
| Parameter/ Return parameter | INT | Internal trigger mode. |
|--------------------------------|-----|------------------------|

| | | |
|--|-----|------------------------|
| | EXT | External trigger mode. |
|--|-----|------------------------|

Example TRIG:SOUR EXT
 Sets the current trigger source to external trigger.

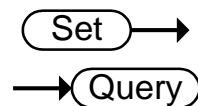
Userdefine Commands

USERdefine<X>:ACTive



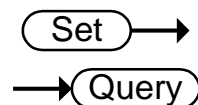
| | | |
|--------------------------------|---|---|
| Description | Sets or returns the active output state of the selected Userdefine pin. | |
| Syntax | USERdefine<X>:ACTive <NR1> | |
| Query Syntax | USERdefine<X>:ACTive? | |
| Parameter/ Return parameter | <X> | Userdefine pin 1~2 |
| | <NR1> | 1:active low state 2:active high state |
| Example | USER1:ACT 1 Sets the userdefine1 pin IO to active low state. | |

USERdefine<X>:FIRStdata



| | | |
|--------------------------------|---|---|
| Description | Sets or returns the first operand for the selected user define pin. | |
| Syntax | USERdefine<X>:FIRStdata <NR1> | |
| Query Syntax | USERdefine<X>:FIRStdata? | |
| Parameter/ Return parameter | <X> | Userdefine pin 1~2 |
| | <NR1> | 1~8:bin1~bin8 state 9:bin out state 10:hi state 11:low state 12:pass state 13:fail state |
| Example | USER1:FIRS 12 Sets first operand of userdefine1 as pass state. | |

USERdefine<X>:LOGic



| | | |
|-------------|--|--|
| Description | Sets or returns operator for the selected user define pin. | |
|-------------|--|--|

| | | |
|--------------------------------|--|---|
| Syntax | USERdefine<X>:LOGic <NR1> | |
| Query Syntax | USERdefine<X>:LOGic? | |
| Parameter/ Return parameter | <X> | Userdefine pin 1~2 |
| | <NR1> | 1:off(only judge first data) 2:logical and. 3:logical or. |
| Example | USER1:LOG 1 Sets the operator of userdefine1 to off. (I.e., only the first operand determines the output of userdefine1.) | |

Set →

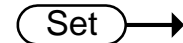
→ Query

USERdefine<X>:SEConddata

| | | |
|--------------------------------|--|---|
| Description | Sets or returns the second operand for the selected user define pin. | |
| Syntax | USERdefine<X>:SEConddata <NR1> | |
| Query Syntax | USERdefine<X>:SEConddata? | |
| Parameter/ Return parameter | <X> | 1~2 |
| | <NR1> | 1~8:bin1~bin8 state 9:bin out state 10:hi state 11:low state 12:pass state 13:fail state |
| Example | USER1:SEC 3 Sets the last operand of userdefine1 as the state of the bin3 result. | |

IEEE 488.2 Common Commands

*CLS

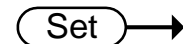


Description Clears the Event Status register (Output Queue, Operation Event Status, Questionable Event Status, Standard Event Status).

Syntax *CLS

Parameter <None>

*ESE



Description Sets or returns the ESER (Event Status Enable Register) contents.

Syntax *ESE <NR1>

Query Syntax *ESE?

Parameter/
Return parameter <NR1> 0~255

Example *ESE 65
Sets the ESER to 01000001
*ESE?
>130
ESER=10000010

*ESR



Description Returns SESR (Standard Event Status Register) contents.

Syntax *ESR?

Query Syntax

Return parameter <NR1> 0~255

Example *ESR?
>198
SESR=11000110

***IDN** → **Query**

Description Returns the manufacturer, model No., serial number and system version number.

Query Syntax *IDN?

Return parameter <String> 31 characters

Example *IDN?
>GWINSTEK,GOM805,GXXXXXXXXX,V1.00.

→ **Set**

***OPC** → **Query**

Description Sets or returns the operation complete bit (bit0) in SERS (Standard Event Status Register) when all pending operations are completed.

Syntax *OPC
Query Syntax *OPC?

Parameter <None>

Return parameter <NR1> 0:operation not complete
1:operation complete

Example *OPC?
Returns 1.

→ **Set**

***RST**

Description Recalls default panel setup.

Syntax *RST

Parameter <None>

→ **Set**

***SRE** → **Query**

Description Sets or returns the SRER (Service Request Enable Register) contents.

| | | |
|--------------------------------|---|-------|
| Syntax | *SRE <NR1> | |
| Query Syntax | *SRE? | |
| Parameter/ Return parameter | <NR1> | 0~255 |
| Example | *SRE 7 Sets the SRER to 00000111 *SRE? >3 SRER=00000011 | |

*STB



| | | |
|------------------|--|-------|
| Description | Returns the SBR (Status Byte Register) contents. | |
| Query Syntax | *STB? | |
| Return parameter | <NR1> | 0~255 |
| Example | *STB? >81 SESR=01010001 | |

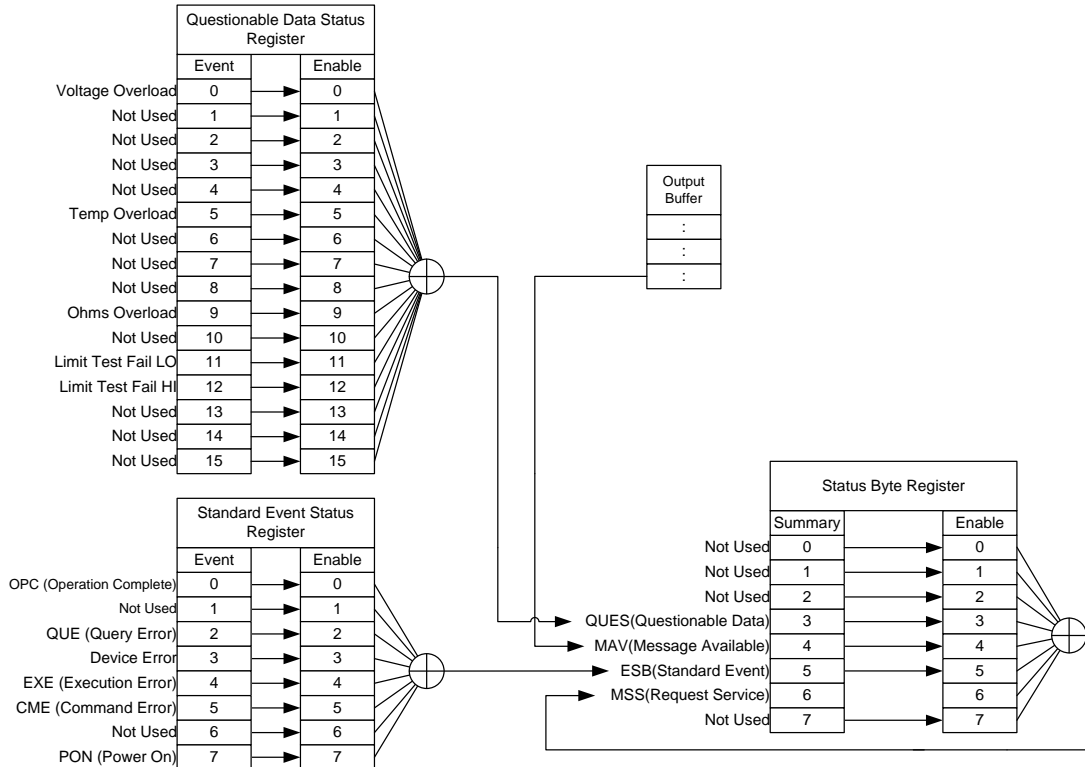
*TRG



| | | |
|-------------|-----------------------------------|--|
| Description | Manually triggers the instrument. | |
| Syntax | *TRG | |
| Parameter | <None> | |

Status system

The diagram below is a description of the status system.



For the following command sets, please refer to the diagram above:

- STAT: QUES: EVEN?
- STAT: QUES: ENAB
- STAT: QUES: ENAB?
- *ESR?
- *ESE
- *ESE?
- *STB?
- *SRE
- *SRE?

FAQ

- What are the different measurement speeds?
- The GOM-804/805 performance does not match the specifications.

What are the different measurement speeds?

There are two measurement speeds for both resistance and temperature measurement. At the slow measurement rate, the measurement speed is 10 samples/s and at the fast measurement rate the measurement speed is at 60 samples/s.

The GOM-804/805 performance does not match the specifications.

Make sure the device is powered on for at least 30 minutes, is operated at the slow measurement rate and is within $+18^{\circ}\text{C}\sim+28^{\circ}\text{C}$ with a humidity not exceeding 80%. This is necessary to stabilize the unit to match the specifications.

APPENDIX

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Temperature Measurement

Reference Temperature Table

Overview The International Temperature Scale (ITS) is based on the
Background following table. The table has 17 fixed calibration points as
of 1990.

| Element | Type | Temperature | |
|--------------------|-------------------------|-------------|-----------|
| | | °K | °C |
| (H ₂) | Hydrogen Triple point | 13.8033 | -259.3467 |
| (Ne) | Neon Triple point | 24.5561 | 248.5939 |
| (O ₂) | Oxygen Triple point | 54.3584 | 218.7916 |
| (Ar) | Argon Triple point | 83.8058 | -189.3442 |
| (Hg) | Mercury Triple point | 234.325 | -38.8344 |
| (H ₂ O) | Water Triple point | 273.16 | +0.01 |
| (Ga) | Gallium Melting point | 302.9146 | 29.7646 |
| (In) | Indium Freezing point | 429.7485 | 156.5985 |
| (Sn) | Tin Freezing point | 505.078 | 231.928 |
| (Zn) | Zinc Freezing point | 692.677 | 419.527 |
| (Al) | Aluminum Freezing point | 933.473 | 660.323 |
| (Ag) | Silver Freezing point | 1234.93 | 961.78 |
| (Au) | Gold Freezing point | 1337.33 | 1064.18 |

RTD Sensors

Overview Resistive Thermal Devices (RTDs) are commonly used as temperature sensors. RTDs change resistance linearly over a specific range of temperature. The table below shows some of the inherent features of RTDs compared to thermocouples.

| Feature | Description |
|------------------------|--------------------------------|
| Accuracy | Higher accuracy |
| Resolution | 0.1~1.0°C, higher resolution |
| Speed of response | Slower |
| Self-heating | Yes |
| Long term stability | Good |
| Output characteristics | Approx. 0.4ohm/°C, near linear |

Optional Platinum Sensor

Introduction The optional platinum sensor is a PT-100 sensor. The PT-100 sensor meets the German DIN43760: 1968 3 wire measurement specification.

These sensors are one of the most common temperature sensors used in industry. These sensors have a nominal resistance of 100Ω at 0°C.

The relationship between temperature and resistance for the PT-100 sensor can be described with the Gallendarvan Dusen equation shown below:

$$R_{RTD} = R_0 [1 + AT + BT^2 + CT^3 (T - 100)]$$

Where: R_{RTD} is the calculated resistance of the RTD.

R_0 is the known RTD resistance at 0°C.

T is the temperature in °C

$A = \alpha [1 + (\delta/100)]$

$B = -1(\alpha)(\delta)(1e-4)$

$C = -1(\alpha)(\beta)(1e-8)$

The Alpha (A), Beta (B), Delta (D) values for the

PT-100 sensor are listed below:

| Type | Standard | Alpha | Beta | Delta | Ω @ 0°C |
|--------|----------|----------|---------|---------|----------------|
| PT-100 | ITS90 | 0.003850 | 0.10863 | 1.49990 | 100 Ω |

Temperature Calculation Example Example—Calculating the resistance of a PT-100 RTD at 100°C (T). The following R_0 (Ω at 0°C), alpha, beta, and delta values are used for the PT-100 RTD:

$$T=100^\circ\text{C}$$

$$R_0 (\Omega \text{ at } 0^\circ\text{C}) = 100\Omega$$

$$\text{Alpha}=0.003850$$

$$\text{Beta}=0.10863$$

$$\text{Delta}=1.49990$$

A, B, and C are calculated according to equations listed above:

$$A=0.00391$$

$$B=5.77\text{e-}7$$

$$C=4.18\text{e-}12$$

The resistance of the RTD at 100°C (R_{100}) is then calculated as follows:

$$\begin{aligned} R_{100}: &= R_0[1+AT=BT^2+CT^3(T-100)] \\ &= 100\{1+[(0.00391)(100)]+[-5.77\text{e-}7)(100^2) \\ &\quad +[(-4.18\text{E-}12)(100^3)(100-100)]\} \\ &= 138.5\Omega \end{aligned}$$

Specifications

Conditions Background

The specifications are applicable under the following conditions:

- A 1-year calibration cycle.
- An operating temperature of 18 to 28 °C (64.4 to 82.4°F).
- Relative humidity not exceeding 80%.
- Accuracy is expressed as \pm (percentage of reading + digits).
- The instrument requires 30 minutes warm-up time and must be operated at the slow measurement rate to achieve rated accuracy.
- The power cord protective grounding conductor must be connected to ground.

Resistance Measurement

50000 counts

| Range | Resolution | Measuring Current | Accuracy | Open-Terminal Voltage |
|---------------|-----------------|-------------------|-----------------------|-----------------------|
| 50m Ω | 1 $\mu\Omega$ | 1A | $\pm(0.1\%+0.02\%)$ | ~6.5V |
| 500m Ω | 10 $\mu\Omega$ | 100mA | $\pm(0.05\%+0.02\%)$ | ~6.5V |
| 5 Ω | 100 $\mu\Omega$ | 10mA | $\pm(0.05\%+0.02\%)$ | ~6.5V |
| 50 Ω | 1m Ω | 1mA | $\pm(0.05\%+0.02\%)$ | ~6.5V |
| 500 Ω | 10m Ω | 1mA | $\pm(0.05\%+0.008\%)$ | ~6.5V |
| 5k Ω | 100m Ω | 1mA | $\pm(0.05\%+0.008\%)$ | ~6.5V |
| 50k Ω | 1 Ω | 100 μ A | $\pm(0.05\%+0.008\%)$ | ~6.5V |
| 500k Ω | 10 Ω | 10 μ A | $\pm(0.05\%+0.008\%)$ | ~6.5V |
| 5M Ω | 100 Ω | 1 μ A | $\pm(0.2\%+0.008\%)$ | ~6.5V |

*When the instrument is set to 50m Ω or 500m Ω ranges, the resistance value will be changed while connecting or disconnecting the test lead to the panel due to the different temperature between internal and external parts of the instrument. Therefore, please wait 1 minute in order to obtain an accurate value after the test leads have been connected or disconnected.

* When Kelvin clips are used to resume testing after a long period of time, please wait for a short time to stabilize the measurement.

*Fast and Slow measurement rates have the same specifications. However, the Slow rate is more accurate as it will correct for any errors associated with temperature drift that occurs from the difference between the measurement

temperature and the calibration temperature.

| | |
|------------------------|---|
| Measurement | Four-terminal method. |
| Auto-ranging | Provided. |
| Over input range | “-----” indicates over range |
| Comparator | 20 sets of comparator status can be selected. |
| Buzzer mode switchable | OFF, PASS, FAIL |

Dry Resistance Measurement

| Range | Measuring Current | Accuracy |
|-------|-------------------|---------------|
| 500mΩ | 100mA | ±(0.3%+0.05%) |
| 5Ω | 10mA | ±(0.3%+0.05%) |
| 50Ω | 1mA | ±(0.3%+0.05%) |

Temperature Measurement

| | |
|-----------------------------|---|
| Temperature sensor (option) | Platinum resistor. Lead length: 1.5m approx. |
| -10°C ~40°C | 0.3%±0.5°C |
| Other | 0.3%±1.0°C |

Temperature Correction Function

| | |
|-----------------------------|---|
| Reference temperature range | -50.0°C~399.9°C |
| Thermal coefficient range | ±9999 ppm |
| Temperature range | Accuracy of temperature compensation for 3930 ppm/Cu wire.* |
| -10°C~40.0°C | 0.3%+resistance measurement accuracy. |
| Other | 0.6%+resistance measurement accuracy. |

*The temperature coefficient for the other settings must be calculated individually according to different conditions.

*If the temperature coefficient or the difference between the environmental temperature and the required temperature exceeds normal operation, after calculating the compensation, the variation to the reading value will be significant.

*When using the PT-100 temperature sensor for temperature measurements, the accuracy of the sensor (typical accuracy of $\pm 0.5^{\circ}\text{C}$) should also be taken into account and calculated for.

Interface

| | |
|-----------------------------|--|
| Handler interface* | Signal: Trigger: TTL input Signal: LOW, HIGH, FAIL, PASS, EOT, READY, BIN 1~8, BIN OUT: total 15 TTL outputs. |
| Scan* | Signal: RELAY, PASS, LOW, HIGH, CLOCK, STRB total 6 TTL outputs. |
| Communication Interfaces | GOM-804: USB/RS-232 GOM-804G: USB/RS-232/GPIB GOM-805: USB/RS-232/GPIB *The Scan and Handler interface use the same connector. |

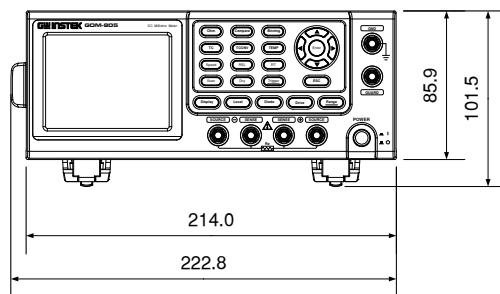
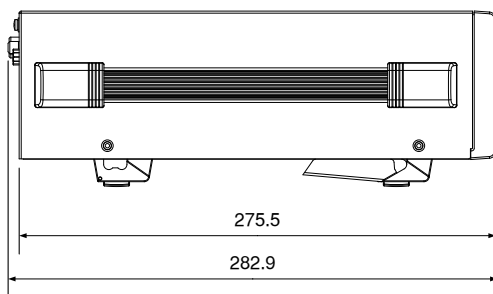
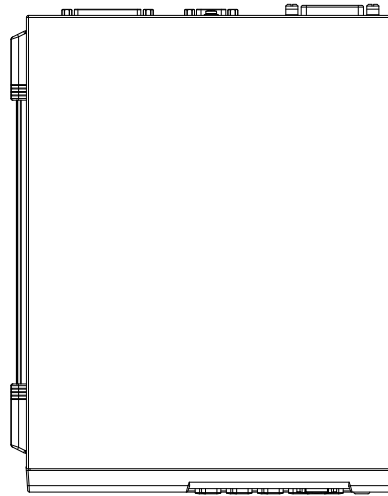
Environmental

| | |
|--------------------------|---|
| Operation Environment | Indoor use, altitude up to 2000m. Ambient Temperature 0 °C to 40 °C. Relative Humidity 80% (Maximum). Pollution Degree 2 |
| Storage temperature | -10 °C to 70 °C. |

General

| | |
|--------------|--|
| Power source | AC 100-240V±10%, 50-60Hz, 25VA |
| Accessories | Power cord x1 Test lead: GTL-308 x1 User manual x1 (CD) Safety instruction sheet x1 USB cable (option): GTL-246 Temperature sensor (option): PT-100 |
| Dimension | 223(W)×102(H)×283(D) mm |
| Weigh | Approx. 3 kg |

Dimensions



Declaration of Conformity

We
COMBINED TEST SOLUTIONS
 declare, that the below mentioned product
 Type of Product: **DC Milliohm Meter**
 Model Number: **GOM-804, GOM-805**
 are herewith confirmed to comply with the requirements set out in the
 Council Directive on the Approximation of the Law of Member States
 relating to Electromagnetic Compatibility (2004/108/EC) & (2014/30/EU)
 and Low Voltage Directive (2006/95/EC) & (2014/35/EU).
 For the evaluation regarding the Electromagnetic Compatibility and Low
 Voltage Equipment Directive, the following standards were applied:

| © EMC | |
|--|---|
| EN 61326-1: EN 61326-2-1: EN 61326-2-2: | Electrical equipment for measurement, control and laboratory use -- EMC requirements (2013) |
| Conducted and Radiated Emission EN 55011: 2009+A1:2010 | Electrostatic Discharge EN 61000-4-2: 2009 |
| Current Harmonics EN 61000-3-2: 2006+A1:2009+A2:2014 | Radiated Immunity EN 61000-4-3 : 2006+A1 :2008+A2 :2010 |
| Voltage Fluctuation EN 61000-3-3 :2013 | Electrical Fast Transients EN 61000-4-4: 2012 |
| ----- | Surge Immunity EN 61000-4-5 :2006 |
| ----- | Conducted Susceptibility EN 61000-4-6 : 2014 |
| ----- | Power Frequency Magnetic Field EN 61000-4-8: 2010 |
| ----- | Voltage Dip/ Interruption EN 61000-4-11: 2004 |

| Low Voltage Equipment Directive 2006/95/EC & 2014/35/EU | |
|---|--|
| Safety Requirements | EN 61010-1: 2010 EN 61010-2-030: 2010 |

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